ICRA 2021 Awards

IEEE ICRA Best Paper Award on Human-Robot Interaction (HRI) -Finalists (sponsored by ABB)

 Can I Pour into It? Robot Imagining Open Containability Affordance of Previously Unseen Objects Via Physical Simulations

Hongtao Wu and Gregory Chirikjian

 Collision Detection, Identification, and Localization on the DLR SARA Robot with Sensing Redundancy

Maged Iskandar, Oliver Eiberger, Alin Albu-Schäffer, Alessandro De Luca and Alexander Dietrich

 Automated Acquisition of Structured, Semantic Models of Manipulation Activities from Human VR Demonstration

Andrei Haidu and Michael Beetz

Reactive Human-To-Robot Handovers of Arbitrary Objects

Wei Yang, Chris Paxton, Arsalan Mousavian, Yu-Wei Chao, Maya Cakmak and

Dieter Fox





