

CTL MODEL CHECKING

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M. Benerecetti, A. Cimatti, M. Fisher, F. Giunchiglia, M. Pistore, M. Roveri, R. Sebastiani.*

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Summary

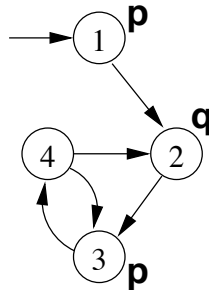
- CTL Model Checking: General Ideas.
- CTL Model Checking: The Labeling Algorithm.
- Labeling Algorithm in Details.
- CTL Model Checking: Theoretical Issues.

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CTL Model Checking

CTL Model Checking is a formal verification technique s.t.

- The system is represented as a Kripke Model \mathcal{KM} :



- The property is expressed as a CTL formula φ , e.g.:

$$\mathbf{AG}(p \Rightarrow \mathbf{AF}q)$$

- The algorithm checks whether **all** the initial states, s_0 , of the Kripke model satisfy the formula ($\mathcal{KM}, s_0 \models \varphi$).

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CTL M.C. Algorithm: General Ideas

The algorithm proceeds along two macro-steps:

1. Construct the set of states where the formula holds:

$$[[\varphi]] := \{s \in S : \mathcal{KM}, s \models \varphi\}$$

($[[\varphi]]$ is called the **denotation** of φ);

2. Then compare the denotation with the set of initial states:

$$I \subseteq [[\varphi]] ?$$

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CTL M.C. Algorithm: General Ideas

To compute $[[\varphi]]$ proceed “bottom-up” on the structure of the formula, computing $[[\varphi_i]]$ for each subformula φ_i of φ .

For example, to compute $[[\mathbf{AG}(p \Rightarrow \mathbf{AF}q)]]$ we need to compute:

- $[[q]]$,
- $[[\mathbf{AF}q]]$,
- $[[p]]$,
- $[[p \Rightarrow \mathbf{AF}q]]$,
- $[[\mathbf{AG}(p \Rightarrow \mathbf{AF}q)]]$

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CTL M.C. Algorithm: General Ideas

To compute each $[[\varphi_i]]$ for generic subformulas:

- Handle boolean operators by standard set operations;
- Handle temporal operators \mathbf{AX} , \mathbf{EX} by computing **pre-images**;
- Handle temporal operators \mathbf{AG} , \mathbf{EG} , \mathbf{AF} , \mathbf{EF} , \mathbf{AU} , \mathbf{EU} , by applying **fixpoint** operators.

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Summary

- CTL Model Checking: General Ideas.
- CTL Model Checking: The Labeling Algorithm.
- Labeling Algorithm in Details.
- CTL Model Checking: Theoretical Issues.

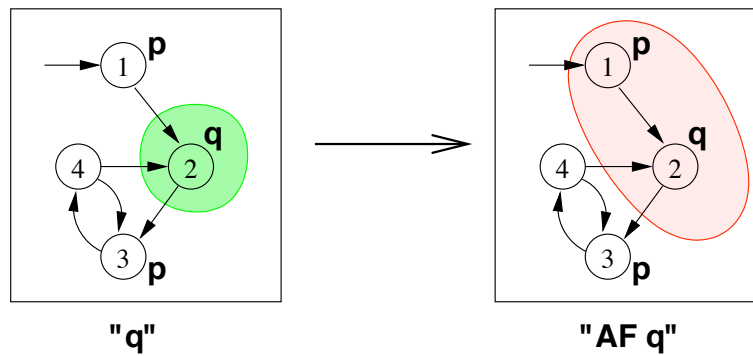
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The Labeling Algorithm: General Idea

- The **Labeling Algorithm** given a Kripke Model and a CTL formula outputs the set of states satisfying the formula.
- **Main Idea:** Label the states of the Kripke Model with the subformulas of φ satisfied there.

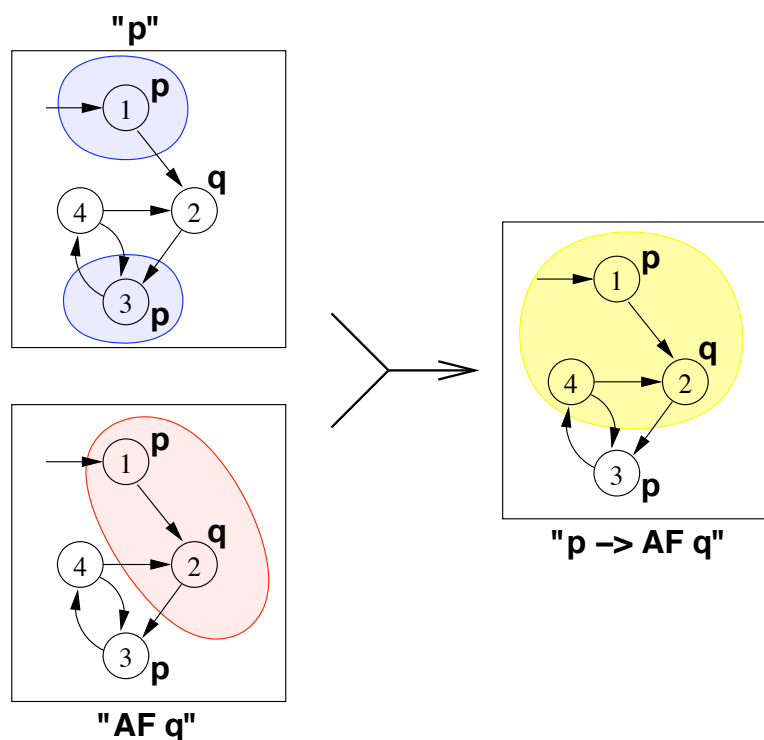
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The Labeling Algorithm: An Example

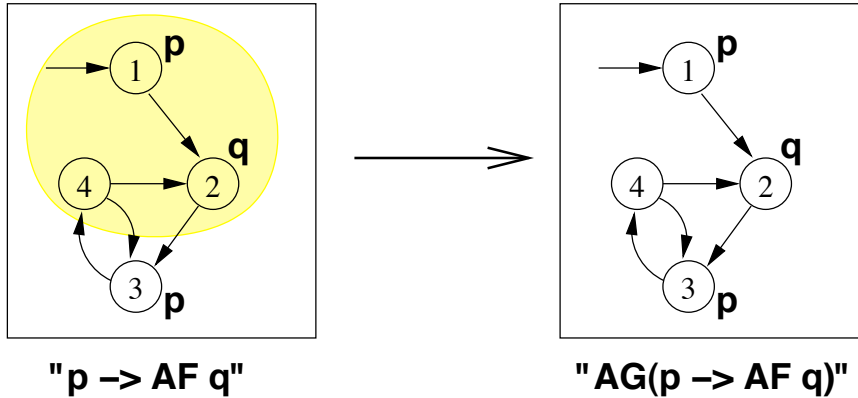


- ▷ $AFq \equiv (q \vee \mathbf{AX}(AFq))$
- ▷ $[[AFq]]$ can be computed as the union of:
 - $[[q]] = \{2\}$
 - $[[q \vee \mathbf{AX}q]] = \{2\} \cup \{1\} = \{1, 2\}$
 - $[[q \vee \mathbf{AX}(q \vee \mathbf{AX}q)]] = \{2\} \cup \{1\} = \{1, 2\}$ (fixpoint).

The Labeling Algorithm: An Example



The Labeling Algorithm: An Example



- ▷ **AG** $\varphi \equiv (\varphi \wedge \mathbf{AX}(\mathbf{AG}\varphi))$
- ▷ $[[\mathbf{AG}\varphi]]$ can be computed as the intersection of of:
 - $[[\varphi]] = \{1, 2, 4\}$
 - $[[\varphi \wedge \mathbf{AX}\varphi]] = \{1, 2, 4\} \cap \{1, 3\} = \{1\}$
 - $[[\varphi \wedge \mathbf{AX}(\varphi \wedge \mathbf{AX}\varphi)]] = \{1, 2, 4\} \cap \{\} = \{\}$ (**fixpoint**)

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The Labeling Algorithm: An Example

- ▷ The set of states where the formula holds is empty, thus:
 - The initial state does not satisfy the property;
 - $\mathcal{KM} \not\models \mathbf{AG}(p \Rightarrow \mathbf{AF}q)$.
- ▷ **Counterexample:** A lazo-shaped path: $1, 2, \{3, 4\}^\omega$ (satisfying $\mathbf{EF}(p \wedge \mathbf{EG}\neg q)$)

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Summary

- CTL Model Checking: General Ideas.
- CTL Model Checking: The Labeling Algorithm.
- **Labeling Algorithm in Details.**
- CTL Model Checking: Theoretical Issues.

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The Labeling Algorithm: General Schema

- ▷ Assume φ written in terms of \neg , \wedge , **EX**, **EU**, **EG** – minimal set of CTL operators
- ▷ The Labeling algorithm takes a CTL formula and a Kripke Model as input and returns the set of states satisfying the formula (i.e., the *denotation* of φ):
 1. For every $\varphi_i \in \text{Sub}(\varphi)$, find $[[\varphi_i]]$;
 2. Compute $[[\varphi]]$ starting from $[[\varphi_i]]$;
 3. Check if $I \subseteq [[\varphi]]$.
- ▷ Subformulas $\text{Sub}(\varphi)$ of φ are checked bottom-up
- ▷ To compute each $[[\varphi_i]]$: if the main operator of φ_i is a
 - *Boolean Operator*: apply standard set operations;
 - *Temporal Operator*: apply recursive rules until a **fixpoint** is reached.

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Denotation of Formulas: The Boolean Case

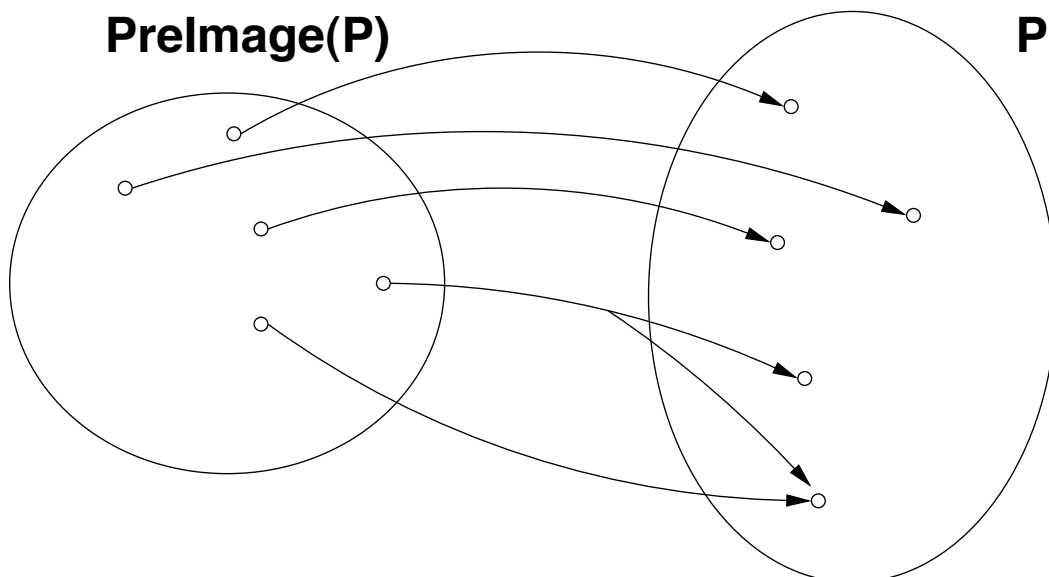
Let $\mathcal{K} \mathcal{M} = \langle S, I, R, L, \Sigma \rangle$ be a Kripke Model.

$$\begin{aligned} \llbracket \text{false} \rrbracket &= \{\} \\ \llbracket \text{true} \rrbracket &= S \\ \llbracket p \rrbracket &= \{s \mid p \in L(s)\} \\ \llbracket \neg \varphi_1 \rrbracket &= S \setminus \llbracket \varphi_1 \rrbracket \\ \llbracket \varphi_1 \wedge \varphi_2 \rrbracket &= \llbracket \varphi_1 \rrbracket \cap \llbracket \varphi_2 \rrbracket \end{aligned}$$

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Denotation of Formulas: The EX Case

- ▷ $\llbracket \mathbf{EX}\varphi \rrbracket = \{s \in S \mid \exists s'. \langle s, s' \rangle \in R \text{ and } s' \in \llbracket \varphi \rrbracket\}$
- ▷ $\llbracket \mathbf{EX}\varphi \rrbracket$ is said to be the **Pre-image of $\llbracket \varphi \rrbracket$** ($\text{PRE}(\llbracket \varphi \rrbracket)$).
- ▷ Key step of every CTL M.C. operation.



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Denotation of Formulas: The EG Case

- From the semantics of the \square temporal operator:

$$\square\varphi \equiv \varphi \wedge \bigcirc(\square\varphi)$$

- Then, the following equivalence holds:

$$\mathbf{EG}\varphi \equiv \varphi \wedge \mathbf{EX}(\mathbf{EG}\varphi)$$

- To compute $[[\mathbf{EG}\varphi]]$ we can apply the following recursive definition:

$$[[\mathbf{EG}\varphi]] = [[\varphi]] \cap \mathbf{PRE}([[\mathbf{EG}\varphi]])$$

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Denotation of Formulas: The EG Case

- We can compute $X := [[\mathbf{EG}\varphi]]$ inductively as follows:

$$X_1 := [[\varphi]]$$

$$X_2 := X_1 \cap \mathbf{PRE}(X_1)$$

...

$$X_{j+1} := X_j \cap \mathbf{PRE}(X_j)$$

- When $X_n = X_{n+1}$ we reach a **fixpoint** and we stop.
- Termination.** Since $X_{j+1} \subseteq X_j$ for every $j \geq 0$, thus **a fixed point always exists** (Knaster-Tarski's theorem).

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Denotation of Formulas: The EU Case

- From the semantics of the \mathcal{U} temporal operator:

$$\varphi \mathcal{U} \psi \equiv \psi \vee (\varphi \wedge \bigcirc(\varphi \mathcal{U} \psi))$$

- Then, the following equivalence holds:

$$(\varphi \mathbf{EU} \psi) \equiv \psi \vee (\varphi \wedge \mathbf{EX}(\varphi \mathbf{EU} \psi))$$

- To compute $\llbracket (\varphi \mathbf{EU} \psi) \rrbracket$ we can apply the following recursive definition:

$$\llbracket (\varphi \mathbf{EU} \psi) \rrbracket = \llbracket \psi \rrbracket \cup (\llbracket \varphi \rrbracket \cap \mathbf{PRE}(\llbracket (\varphi \mathbf{EU} \psi) \rrbracket))$$

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Denotation of Formulas: The EU Case

- We can compute $X := \llbracket (\varphi \mathbf{EU} \psi) \rrbracket$ inductively as follows:

$$X_1 := \llbracket \psi \rrbracket$$

$$X_2 := X_1 \cup (\llbracket \varphi \rrbracket \cap \mathbf{PRE}(X_1))$$

...

$$X_{j+1} := X_j \cup (\llbracket \varphi \rrbracket \cap \mathbf{PRE}(X_j))$$

- When $X_n = X_{n+1}$ we reach a **fixpoint** and we stop.
- Termination.** Since $X_{j+1} \supseteq X_j$ for every $j \geq 0$, thus **a fixed point always exists** (Knaster-Tarski's theorem).

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The Pseudo-Code

We assume the Kripke Model to be a global variable:

```
FUNCTION Label( $\varphi$ ) {
  case  $\varphi$  of
    true:      return  $S$ ;
    false:     return  $\{\}$ ;
    an atom  $p$ : return  $\{s \in S \mid p \in L(s)\}$ ;
     $\neg\varphi_1$ :    return  $S \setminus \text{Label}(\varphi_1)$ ;
     $\varphi_1 \wedge \varphi_2$ : return  $\text{Label}(\varphi_1) \cap \text{Label}(\varphi_2)$ ;
    EX $\varphi_1$ :      return  $\text{PRE}(\text{Label}(\varphi_1))$ ;
    ( $\varphi_1$  EU  $\varphi_2$ ): return  $\text{Label\_EU}(\text{Label}(\varphi_1), \text{Label}(\varphi_2))$ ;
    EG $\varphi_1$ :      return  $\text{Label\_EG}(\text{Label}(\varphi_1))$ ;
  end case
}
```

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PreImage

$\llbracket \text{EX}\varphi \rrbracket = \text{PRE}(\llbracket \varphi \rrbracket) = \{s \in S \mid \exists s'. \langle s, s' \rangle \in R \text{ and } s' \in \llbracket \varphi \rrbracket\}$

```
FUNCTION PRE( $\llbracket \varphi \rrbracket$ ) {
  var  $X$ ;
   $X := \{\}$ ;
  for each  $s' \in \llbracket \varphi \rrbracket$  do
    for each  $s \in S$  such that  $\langle s, s' \rangle \in R$  do
       $X := X \cup \{s\}$ ;
  return  $X$ 
}
```

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Label_EG

$$[[\mathbf{EG}\varphi]] = [[\varphi]] \cap \text{PRE}([[\mathbf{EG}\varphi]])$$

```
FUNCTION LABEL_EG([[φ]]){
  var X, OLD-X;
  X := [[φ]];
  OLD-X := ∅;
  while X ≠ OLD-X
  begin
    OLD-X := X;
    X := X ∩ PRE(X)
  end
  return X
}
```

Label_EU

$$[[\varphi\mathbf{EU}\psi]] = [[\psi]] \cup ([[\varphi]]) \cap \text{PRE}([[\varphi\mathbf{EU}\psi]])$$

```
FUNCTION LABEL_EU([[φ]], [[ψ]]){
  var X, OLD-X;
  X := [[ψ]];
  OLD-X := S;
  while X ≠ OLD-X
  begin
    OLD-X := X;
    X := X ∪ ([[φ]]) ∩ PRE(X)
  end
  return X
}
```

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Correctness and Termination

- The Labeling algorithm works recursively on the structure φ .
- For most of the logical constructors the algorithm does the correct things according to the semantics of CTL.
- To prove that the algorithm is *Correct* and *Terminating* we need to prove the correctness and termination of both **EG** and **EU** operators.

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Monotone Functions and Fixpoints

Definition. Let S be a set and F a function, $F : 2^S \rightarrow 2^S$, then:

1. F is **monotone** iff $X \subseteq Y$ then $F(X) \subseteq F(Y)$;
2. A subset X of S is called a **fixpoint** of F iff $F(X) = X$;
3. X is a **least fixpoint** (LFP) of F , written $\mu X.F(X)$, iff, for every other fixpoint Y of F , $X \subseteq Y$
4. X is a **greatest fixpoint** (GFP) of F , written $\nu X.F(X)$, iff, for every other fixpoint Y of F , $Y \subseteq X$

Example. Let $S = \{s_0, s_1\}$ and $F(X) = X \cup \{s_0\}$.

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Knaster-Tarski Theorem

Notation: $F^i(X)$ means applying F i -times, i.e., $F(F(\dots F(X)\dots))$.

Theorem[Knaster-Tarski]. Let S be a finite set with $n + 1$ elements. If $F : 2^S \rightarrow 2^S$ is a monotone function then:

1. $\mu X.F(X) \equiv F^{n+1}(\emptyset)$;
2. $\nu X.F(X) \equiv F^{n+1}(S)$.

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Correctness and Termination: EG Case

The function LABEL_EG computes:

$$[[\mathbf{EG}\varphi]] = [[\varphi]] \cap \text{PRE}([[\mathbf{EG}\varphi]])$$

applying the semantic equivalence:

$$\mathbf{EG}\varphi \equiv \varphi \wedge \mathbf{EX}(\mathbf{EG}\varphi)$$

Thus, $[[\mathbf{EG}\varphi]]$ is the **fixpoint** of the function:

$$F(X) = [[\varphi]] \cap \text{PRE}(X)$$

Correctness and Termination: EG Case

Theorem. Let $F(X) = [[\varphi]] \cap \text{PRE}(X)$, and let S have $n + 1$ elements. Then:

1. F is monotone;
2. $[[\mathbf{EG}\varphi]]$ is the **greatest fixpoint** of F .

Correctness and Terminationpr: EU Case

The function LABEL_EU computes:

$$\llbracket (\varphi \mathbf{EU} \psi) \rrbracket = \llbracket \psi \rrbracket \cup (\llbracket \varphi \rrbracket \cap \text{PRE}(\llbracket (\varphi \mathbf{EU} \psi) \rrbracket))$$

applying the semantic equivalence:

$$(\varphi \mathbf{EU} \psi) \equiv \psi \vee (\varphi \wedge \mathbf{EX}(\varphi \mathbf{EU} \psi))$$

Thus, $\llbracket (\varphi \mathbf{EU} \psi) \rrbracket$ is the **fixpoint** of the function:

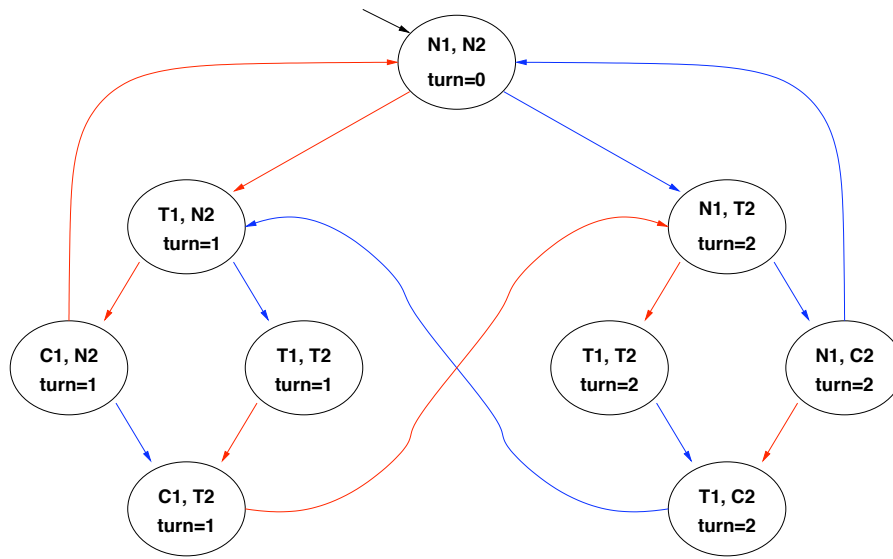
$$F(X) = \llbracket \psi \rrbracket \cup (\llbracket \varphi \rrbracket \cap \text{PRE}(X))$$

Correctness and Termination: EU Case

Theorem. Let $F(X) = \llbracket \psi \rrbracket \cup (\llbracket \varphi \rrbracket \cap \text{PRE}(X))$, and let S have $n + 1$ elements. Then:

1. F is monotone;
2. $\llbracket (\varphi \mathbf{EU} \psi) \rrbracket$ is the **least fixpoint** of F .

Example 1: fairness

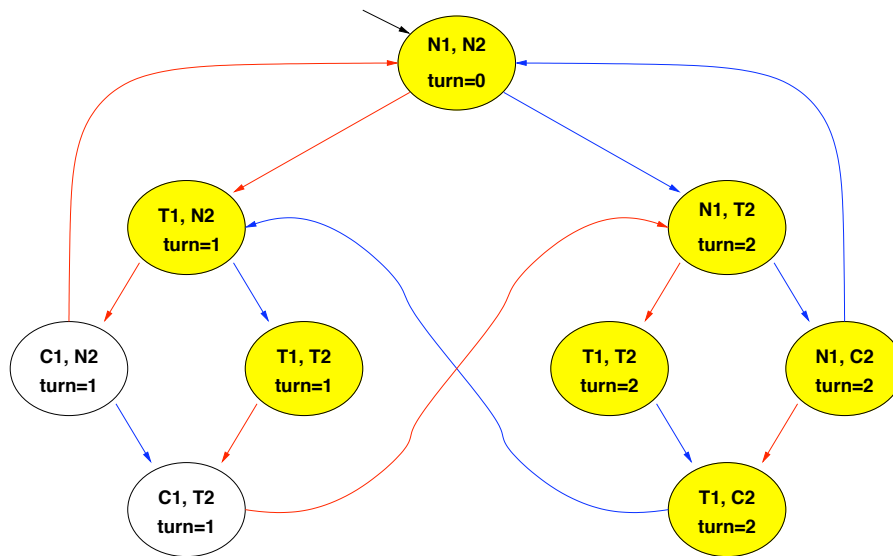


N = noncritical, T = trying, C = critical User 1 User 2

$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

$[\neg C_1]$

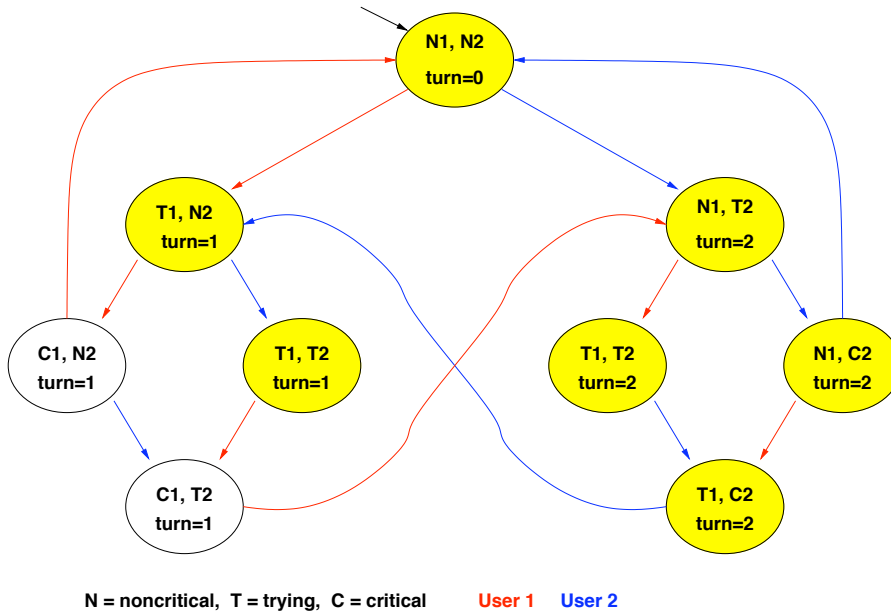


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Example 1: fairness

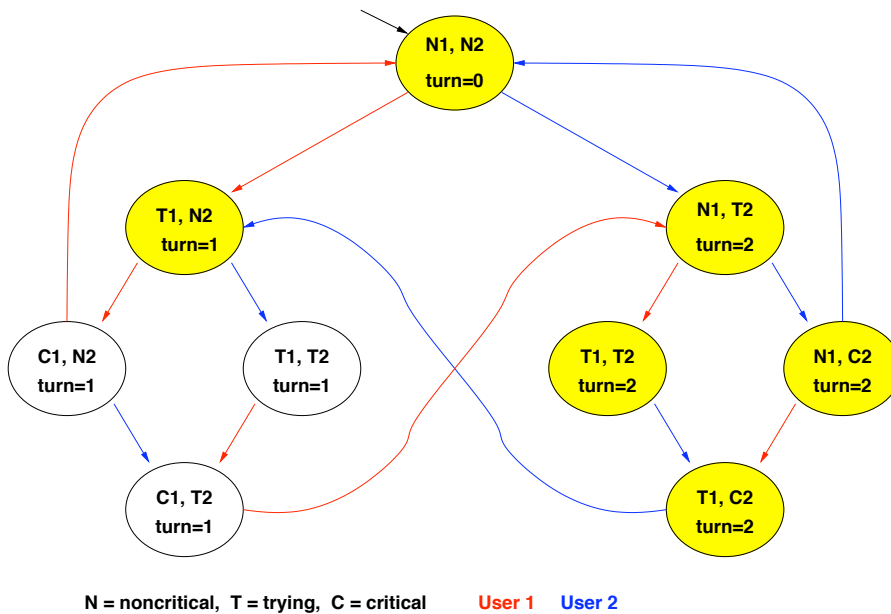
[EG-C₁], step 0:



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

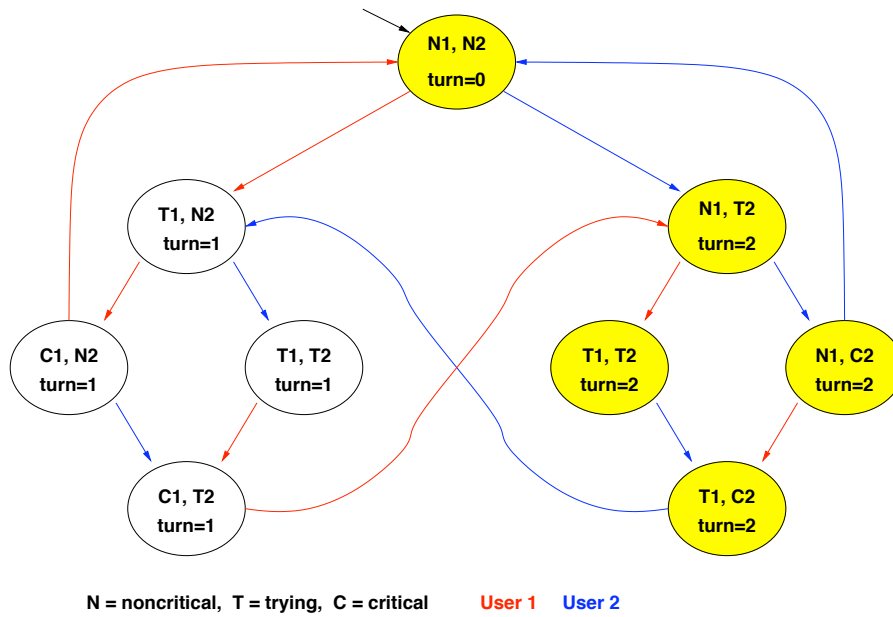
[EG-C₁], step 1:



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Example 1: fairness

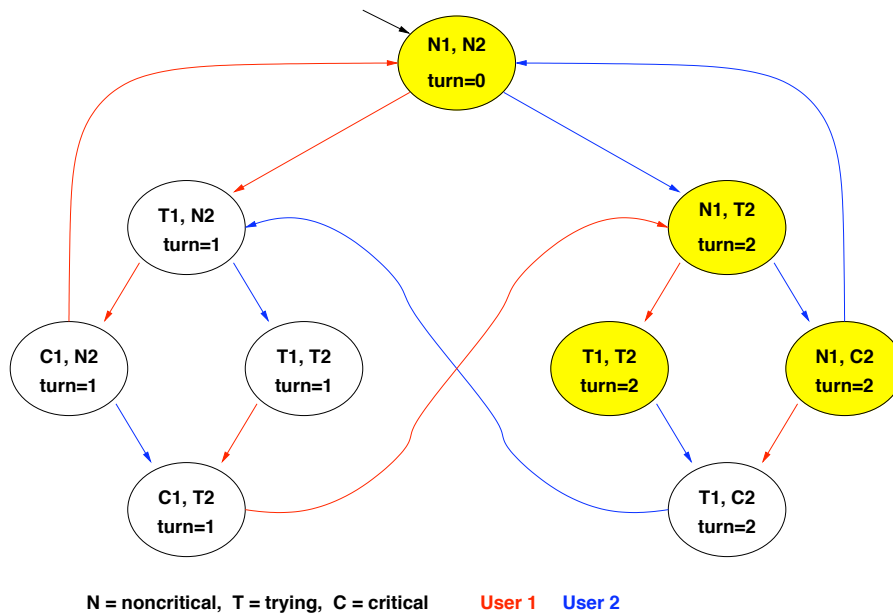
[EG-C₁], step 2:



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

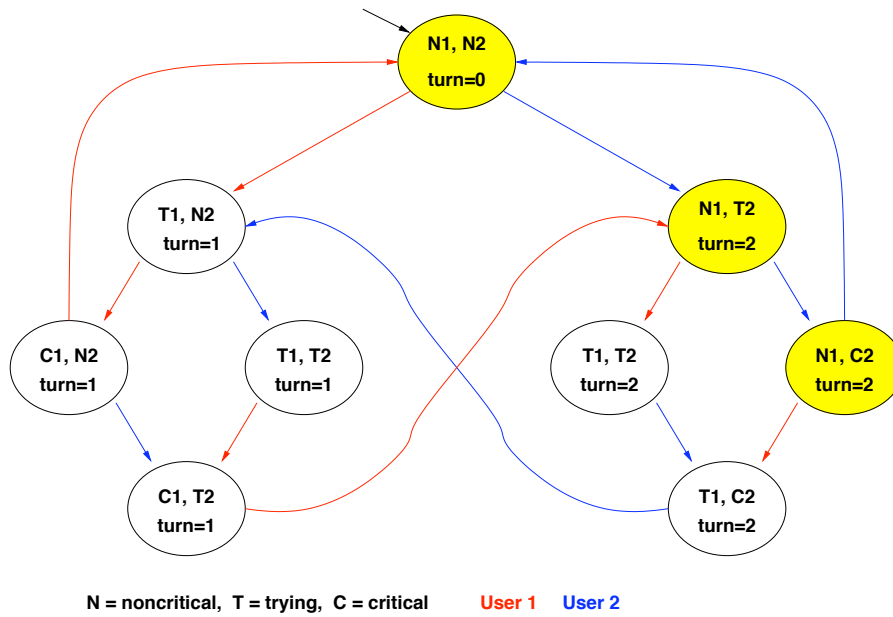
[EG-C₁], step 3:



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

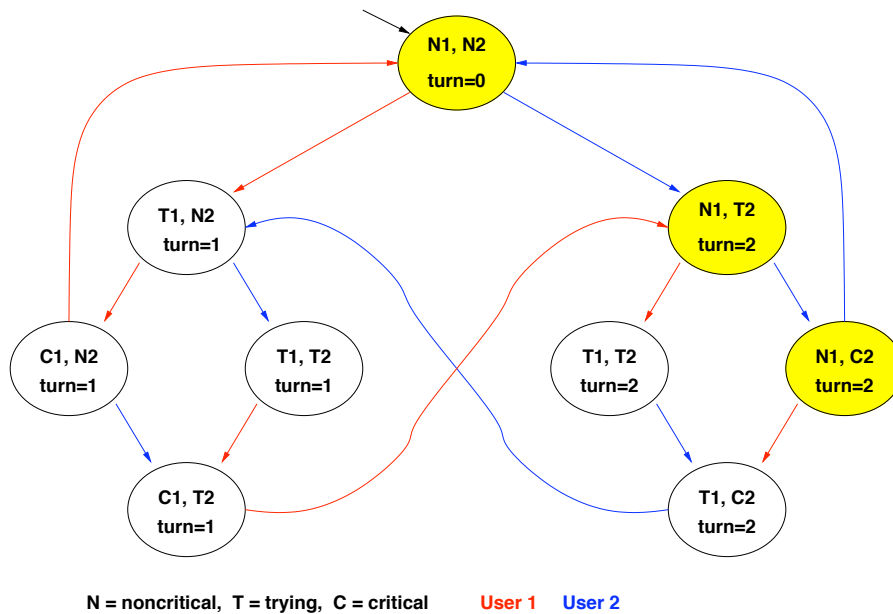
[EG-C₁], step 4:



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

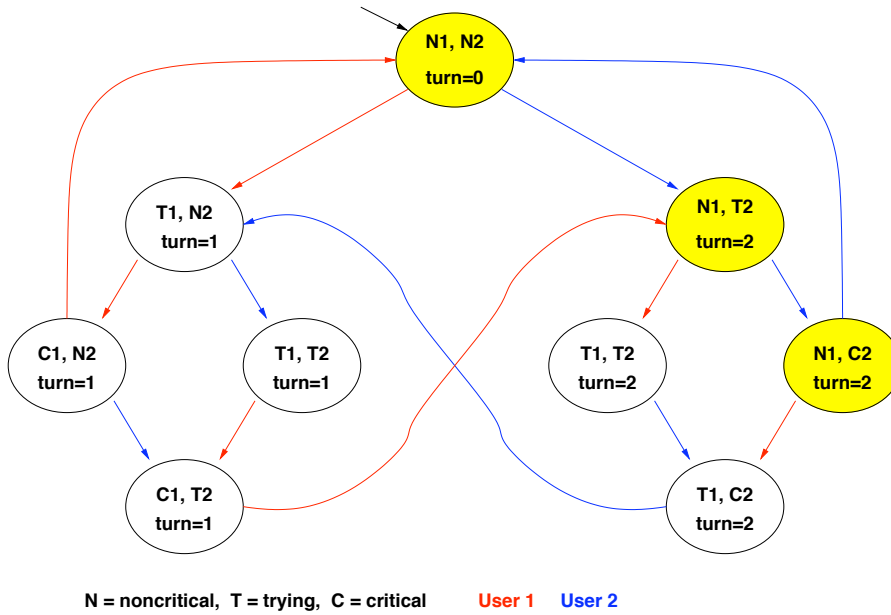
[EG-C₁], FIXPOINT!



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

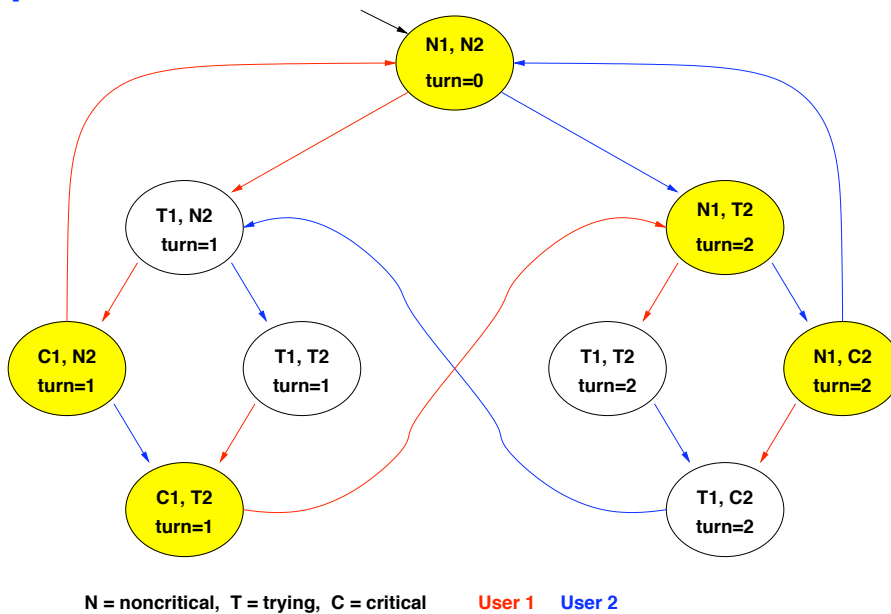
[EFEG-C₁], STEP 0



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

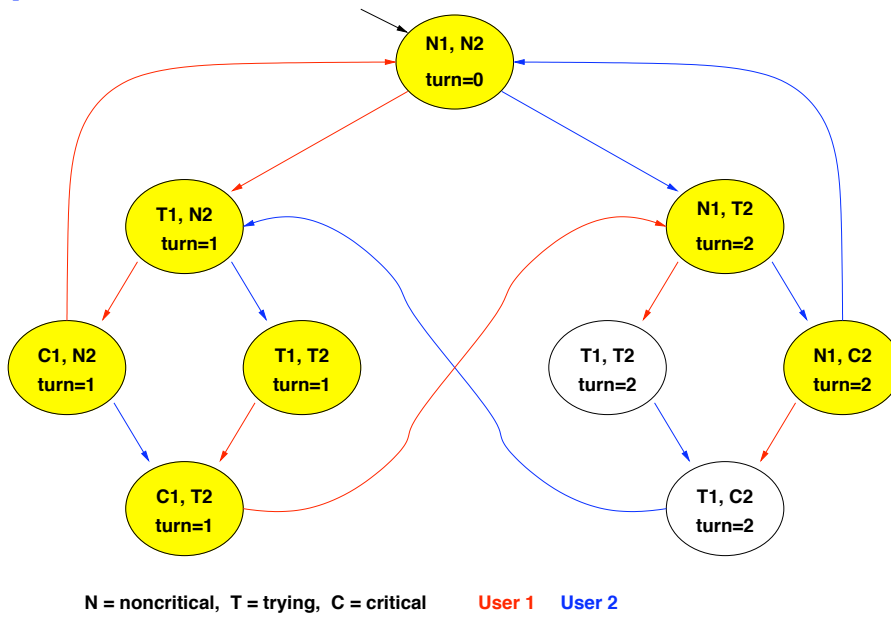
[EFEG-C₁], STEP 1



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

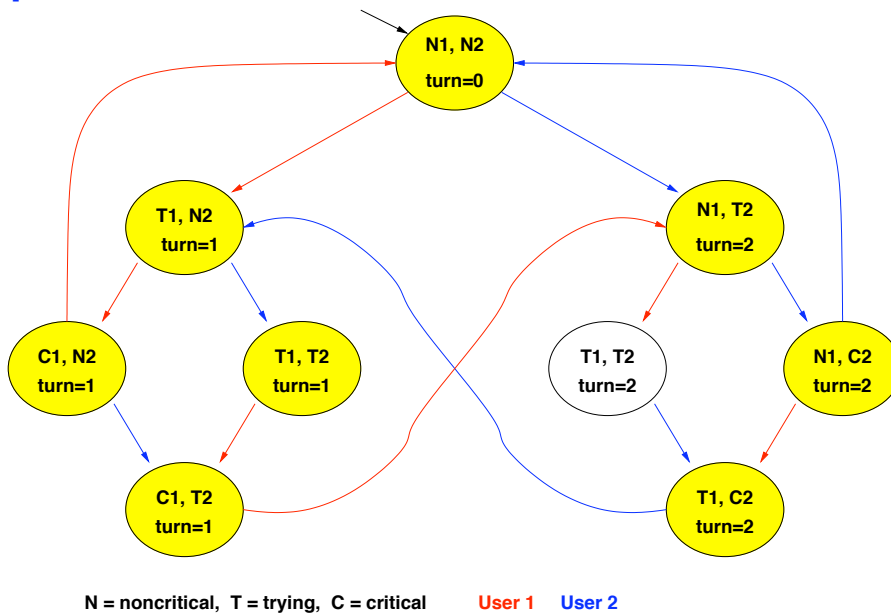
[EFEG- C_1], STEP 2



$$M \models \text{AGAFC}_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

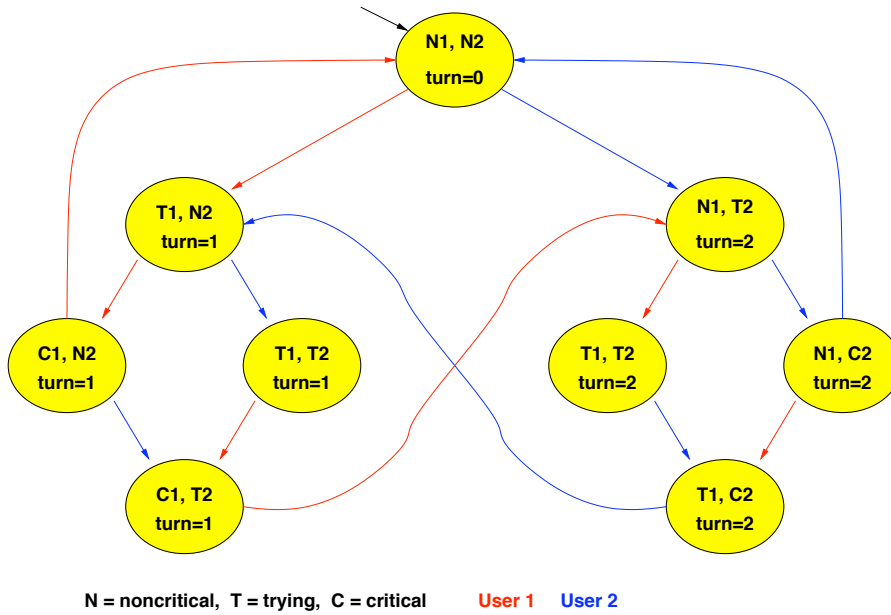
[EFEG- C_1], STEP 3



$$M \models \text{AGAFC}_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

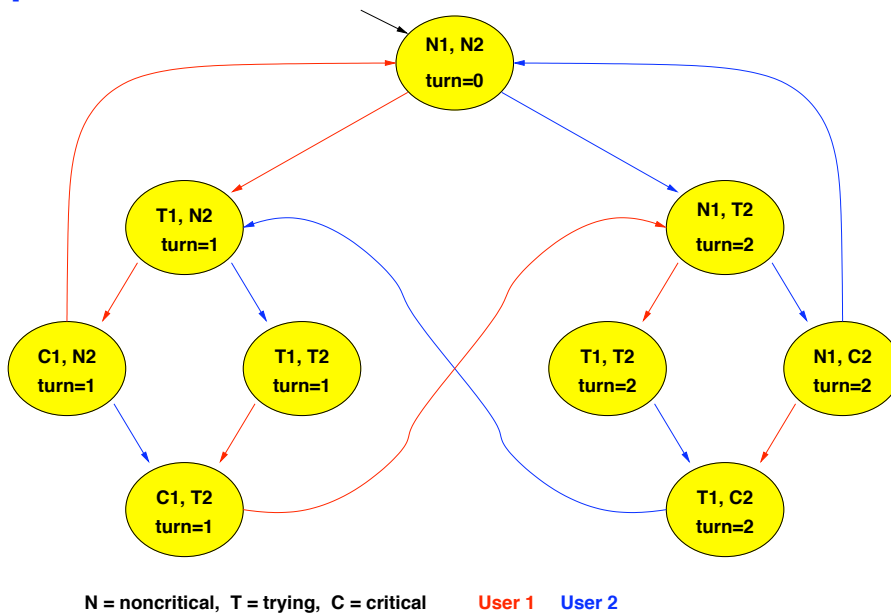
[EFEG-C₁], STEP 4



$$M \models \text{AGAFC}_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

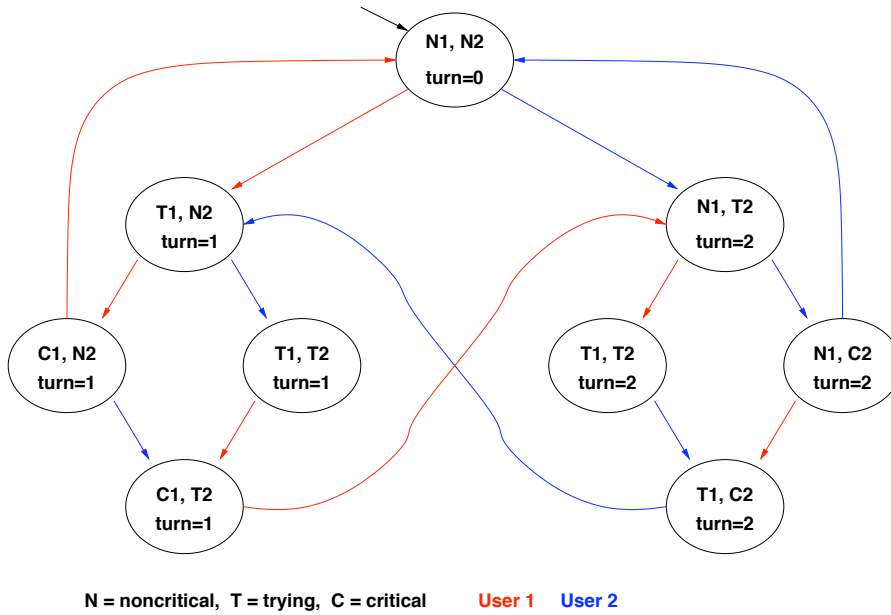
[EFEG-C₁], FIXPOINT!



$$M \models \text{AGAFC}_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

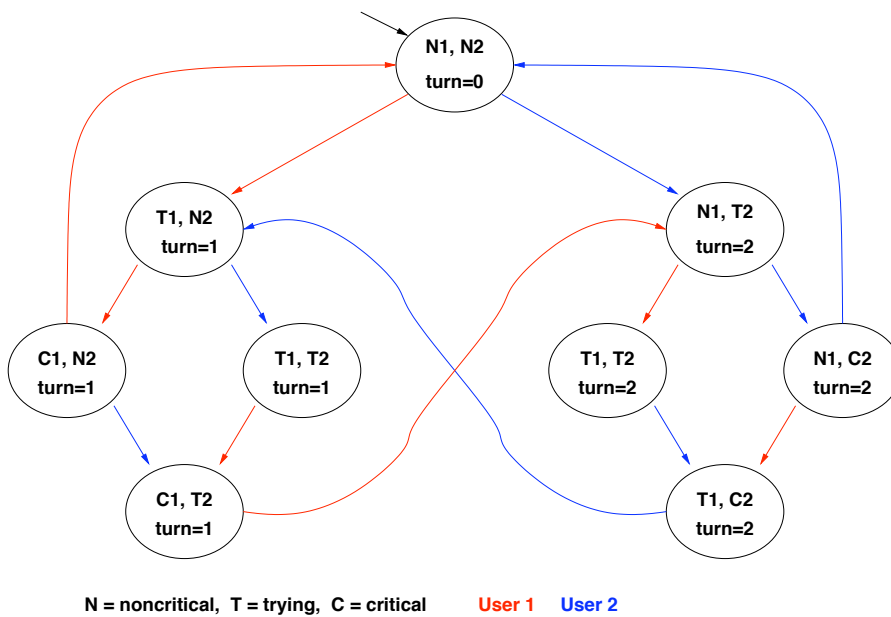
Example 1: fairness

$[\neg\text{EFEG}\neg C_1]$



$M \models \text{AGAF}C_1 ? \implies M \models \neg\text{EFEG}\neg C_1 ? \implies \text{NO!}$

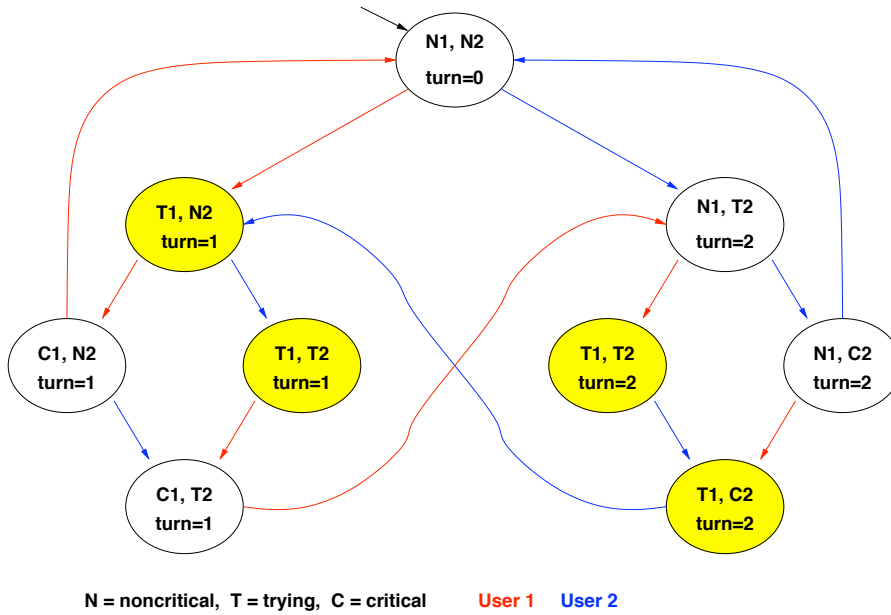
Example 2: liveness



$M \models \text{AG}(T_1 \rightarrow \text{AFC}_1) ? \implies M \models \neg\text{EF}(T_1 \wedge \text{EG}\neg C_1) ?$

Example 2: liveness

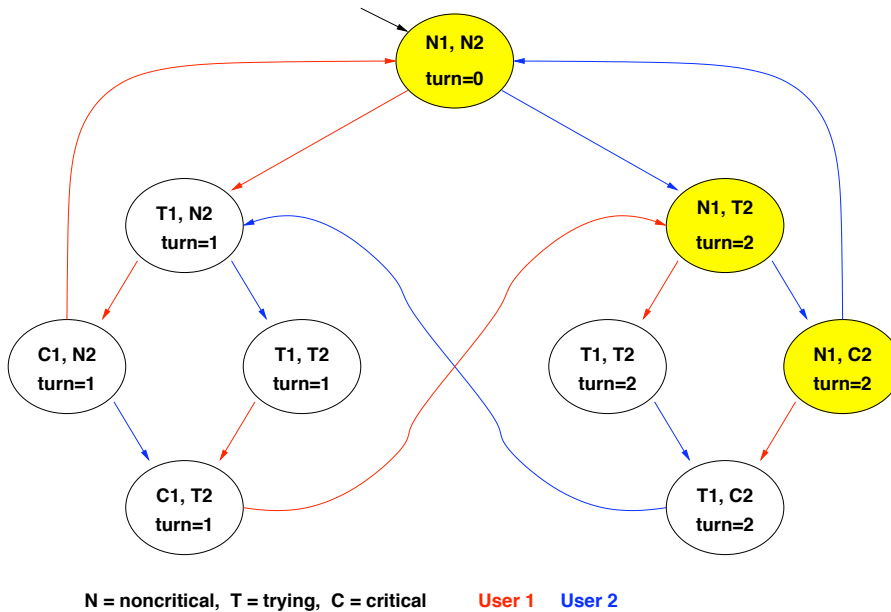
$[T_1]$:



$$M \models \mathbf{AG}(T_1 \rightarrow \mathbf{AFC}_1) ? \implies M \models \neg \mathbf{EF}(T_1 \wedge \mathbf{EG}\neg C_1) ?$$

Example 2: liveness

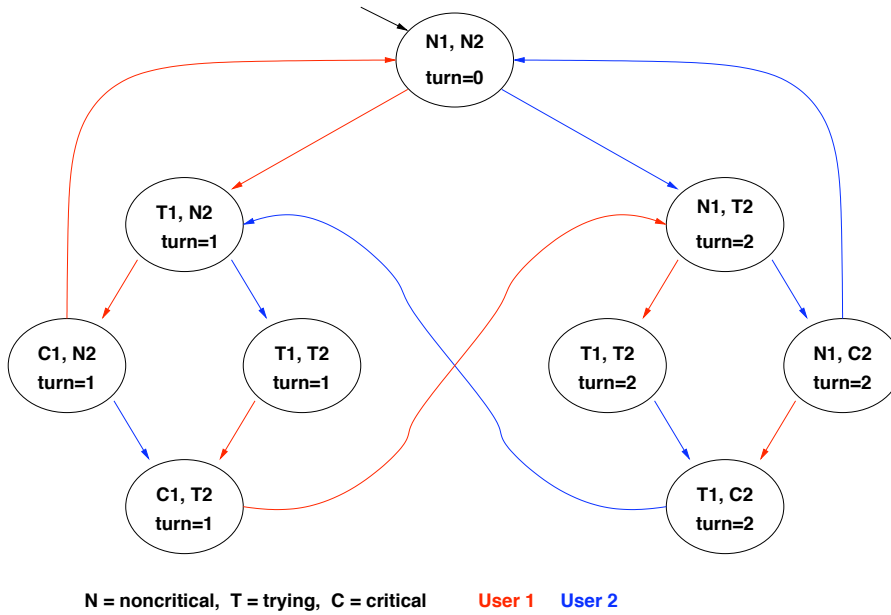
$[\mathbf{EG}\neg C_1]$, STEPS 0-4: (see previous example)



$$M \models \mathbf{AG}(T_1 \rightarrow \mathbf{AFC}_1) ? \implies M \models \neg \mathbf{EF}(T_1 \wedge \mathbf{EG}\neg C_1) ?$$

Example 2: liveness

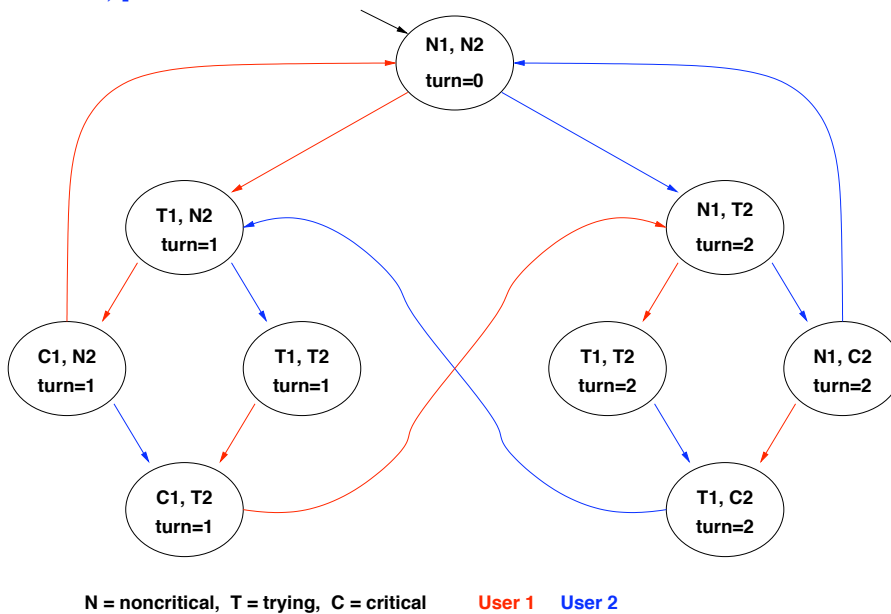
$[T_1 \wedge \mathbf{EG}\neg C_1]$:



$$M \models \mathbf{AG}(T_1 \rightarrow \mathbf{AFC}_1) ? \implies M \models \neg \mathbf{EF}(T_1 \wedge \mathbf{EG}\neg C_1) ?$$

Example 2: liveness

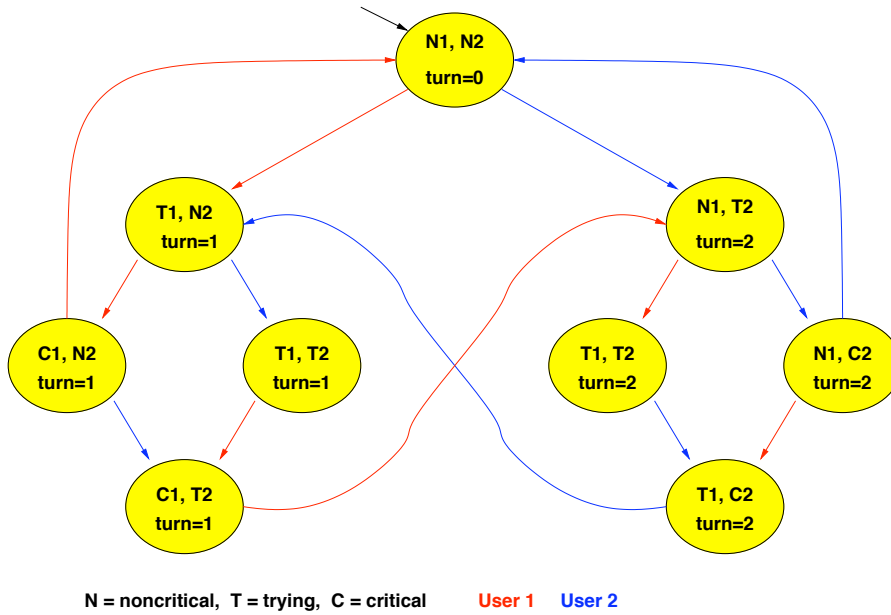
$[\mathbf{EF}(T_1 \wedge \mathbf{EG}\neg C_1)]$:



$$M \models \mathbf{AG}(T_1 \rightarrow \mathbf{AFC}_1) ? \implies M \models \neg \mathbf{EF}(T_1 \wedge \mathbf{EG}\neg C_1) ?$$

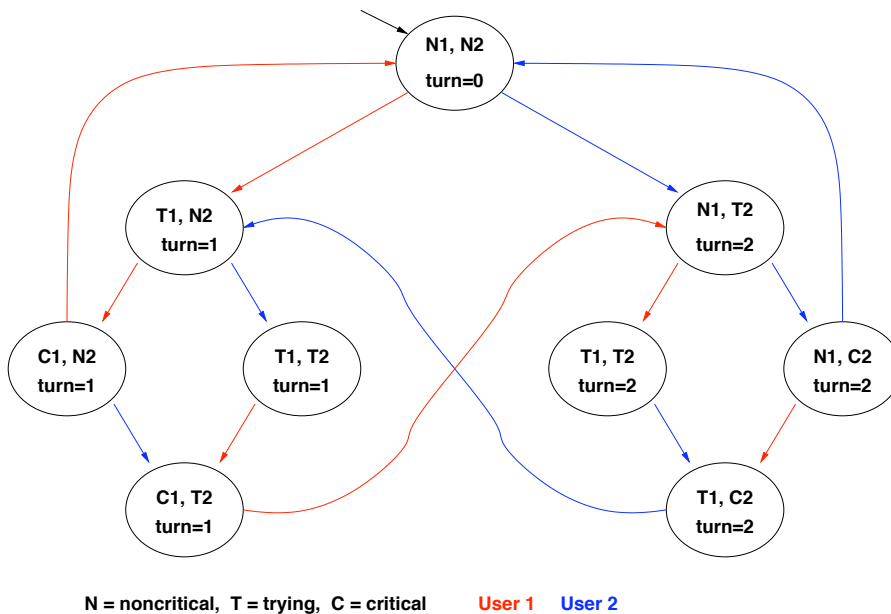
Example 2: liveness

$[\neg \mathbf{EF}(T_1 \wedge \mathbf{EG}\neg C_1)] :$



$M \models \mathbf{AG}(T_1 \rightarrow \mathbf{AFC}_1) ? \implies M \models \neg \mathbf{EF}(T_1 \wedge \mathbf{EG}\neg C_1) ? \text{ YES!}$

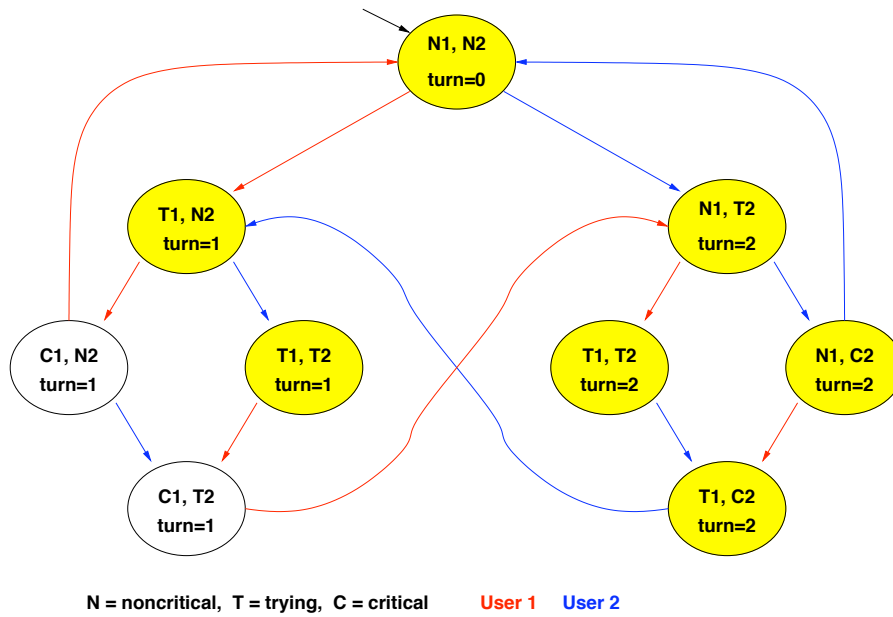
Example 1: fairness



$M \models \mathbf{AGAF}C_1 ? \implies M \models \neg \mathbf{EFEG}\neg C_1 ?$

Example 1: fairness

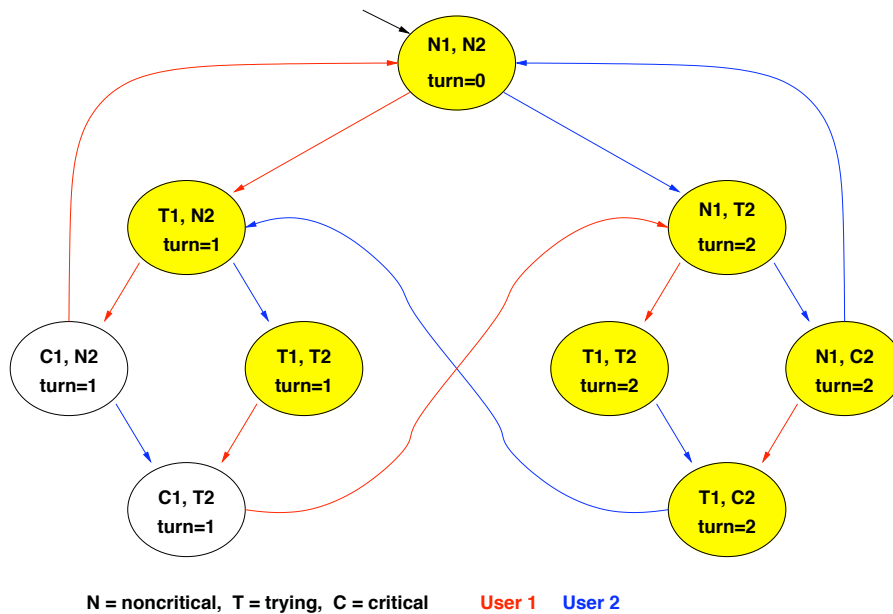
$[\neg C_1]$



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

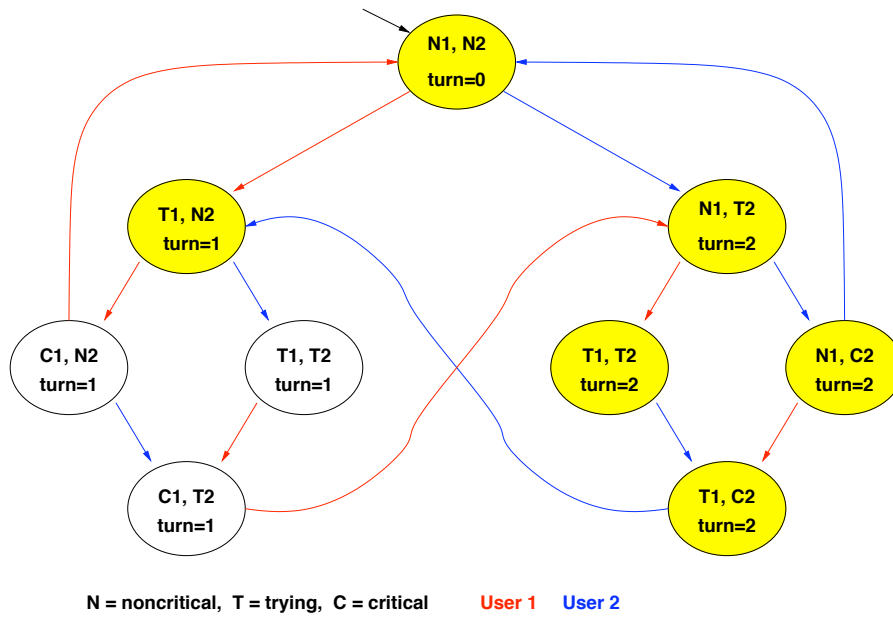
$[\text{EG} \neg C_1]$, step 0:



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

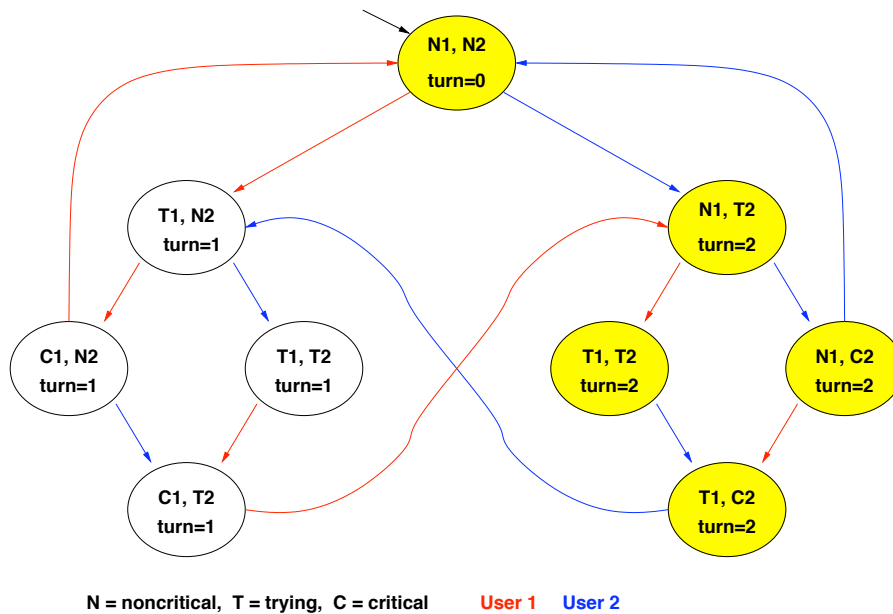
[EG-C₁], step 1:



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

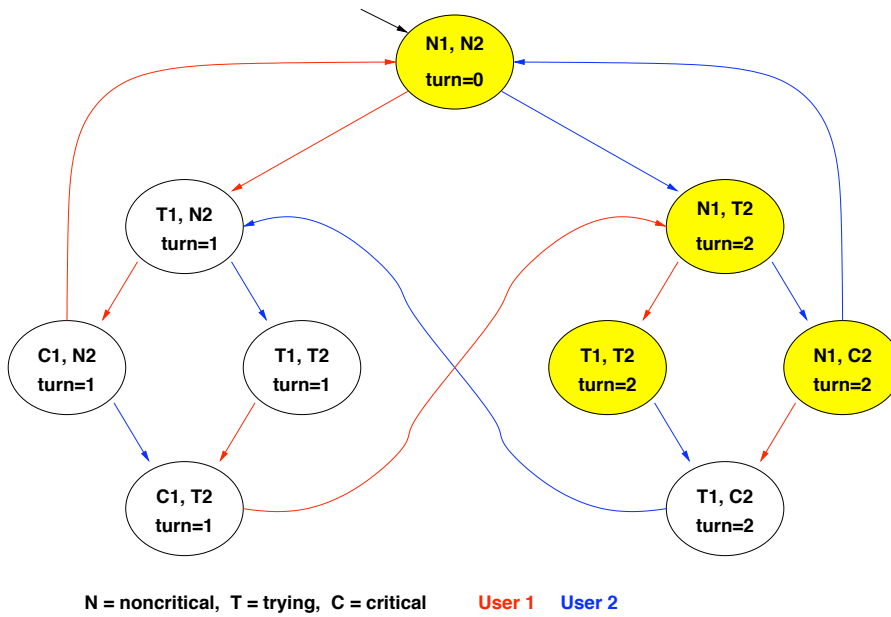
[EG-C₁], step 2:



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

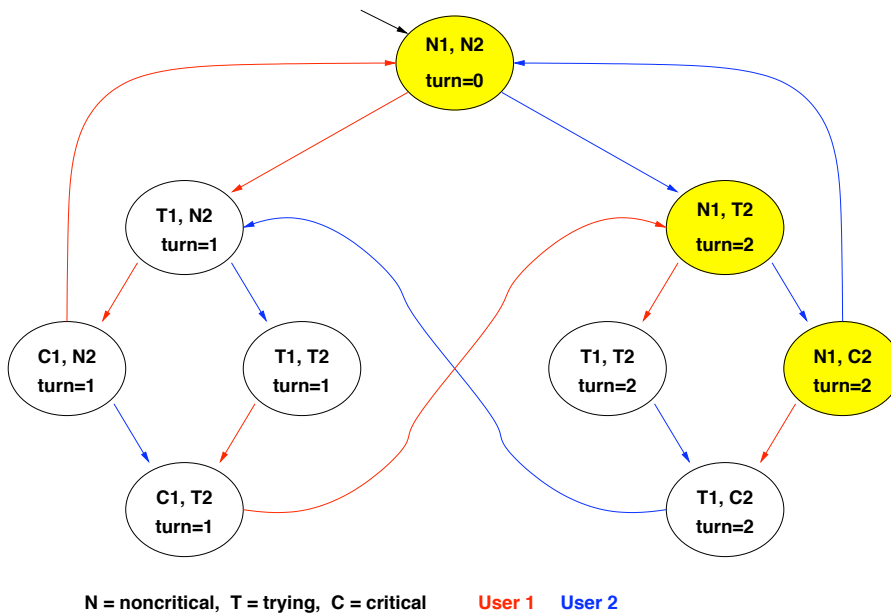
[EG-C₁], step 3:



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

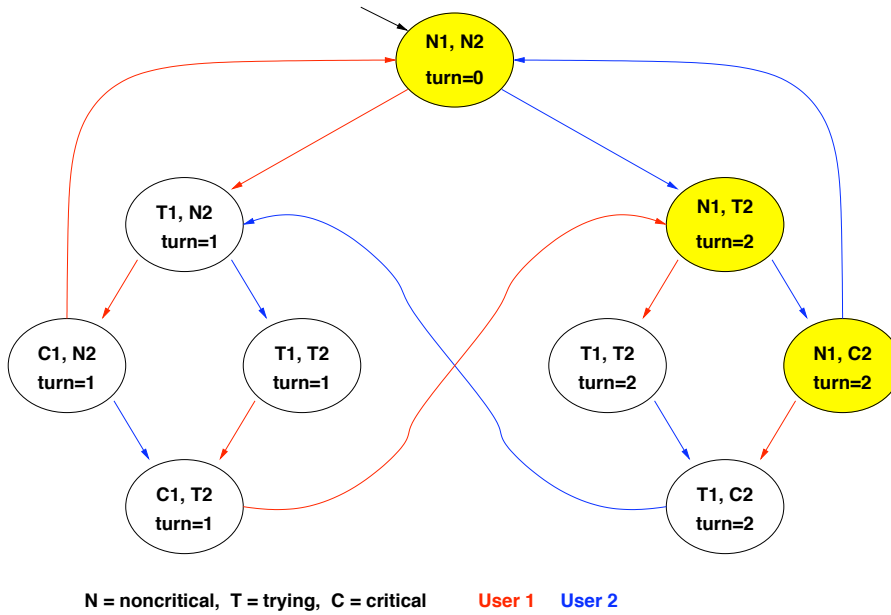
[EG-C₁], step 4:



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

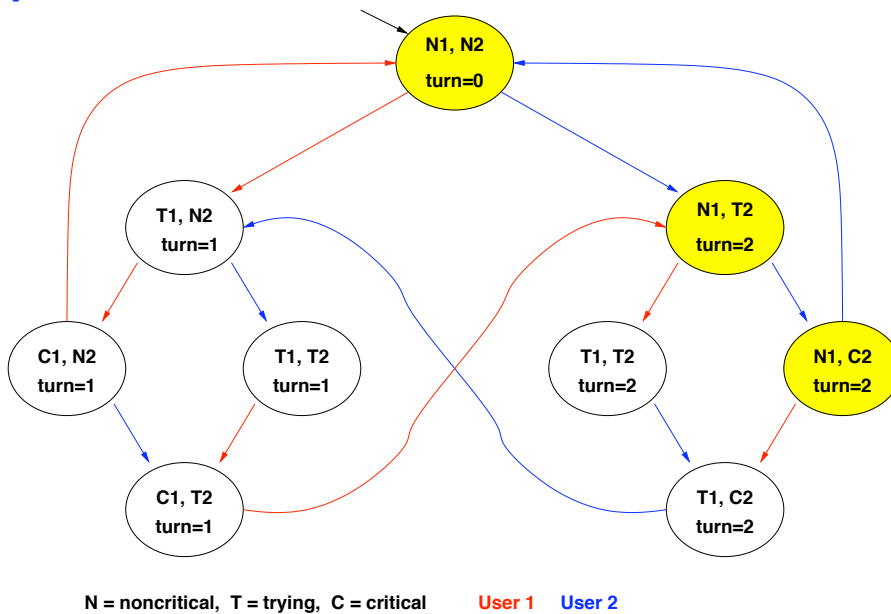
[EG-C₁], FIXPOINT!



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

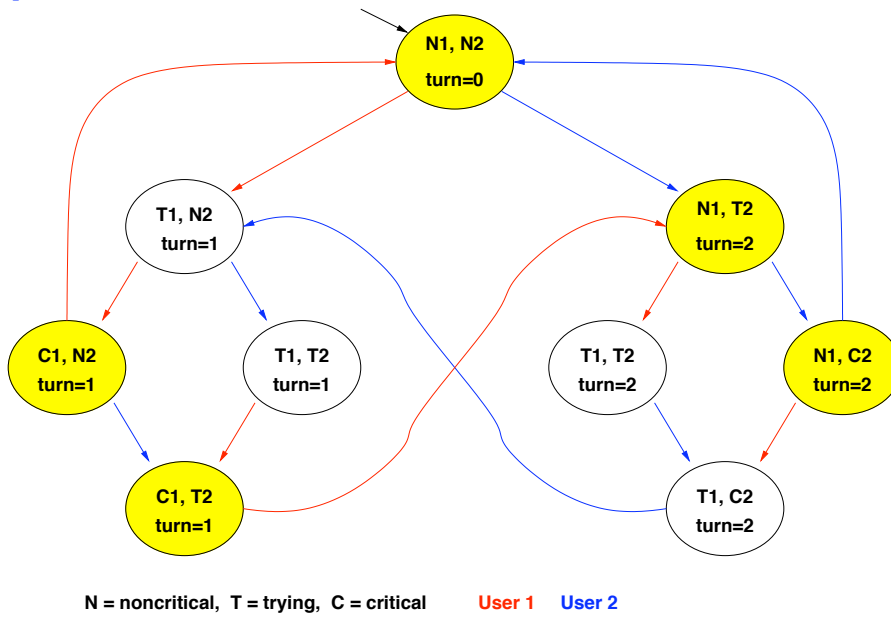
[EFEG-C₁], STEP 0



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

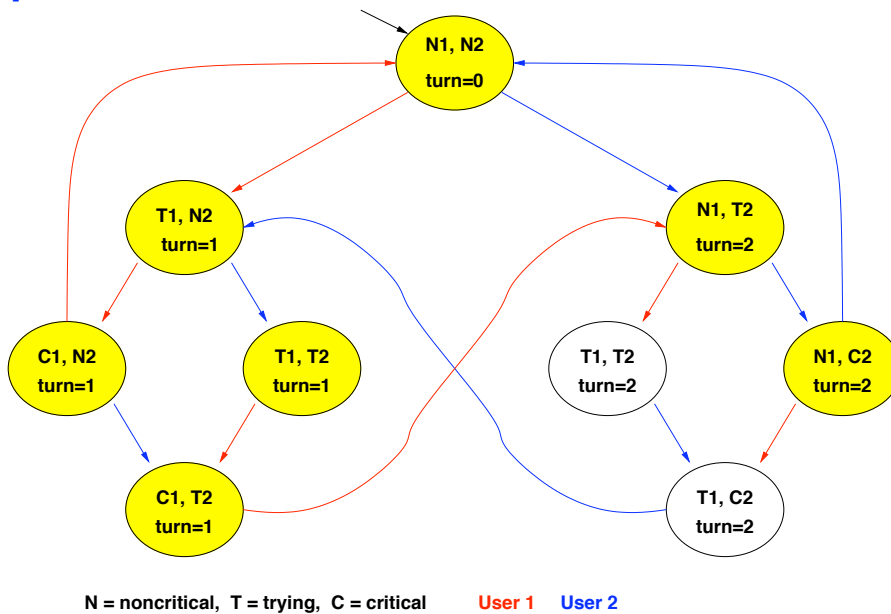
[EFEG-C₁], STEP 1



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

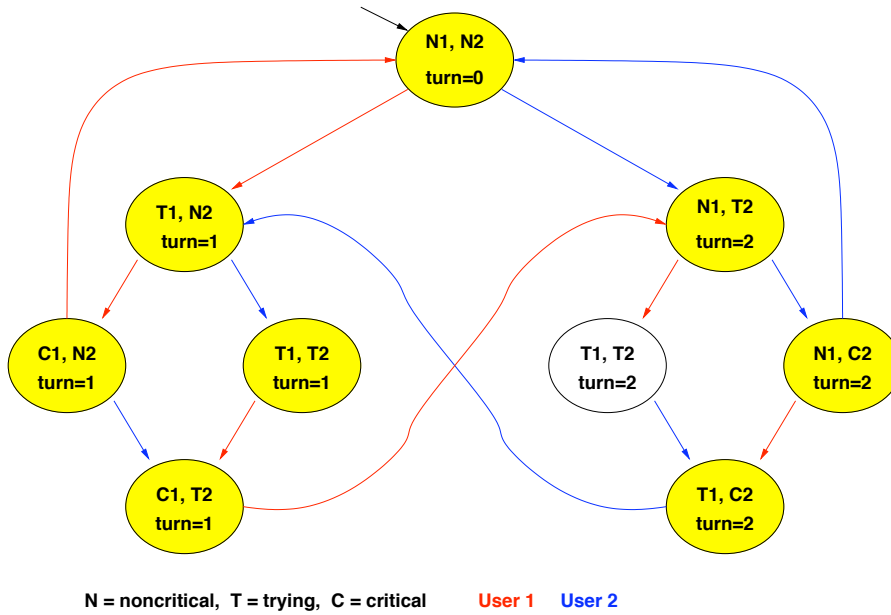
[EFEG-C₁], STEP 2



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

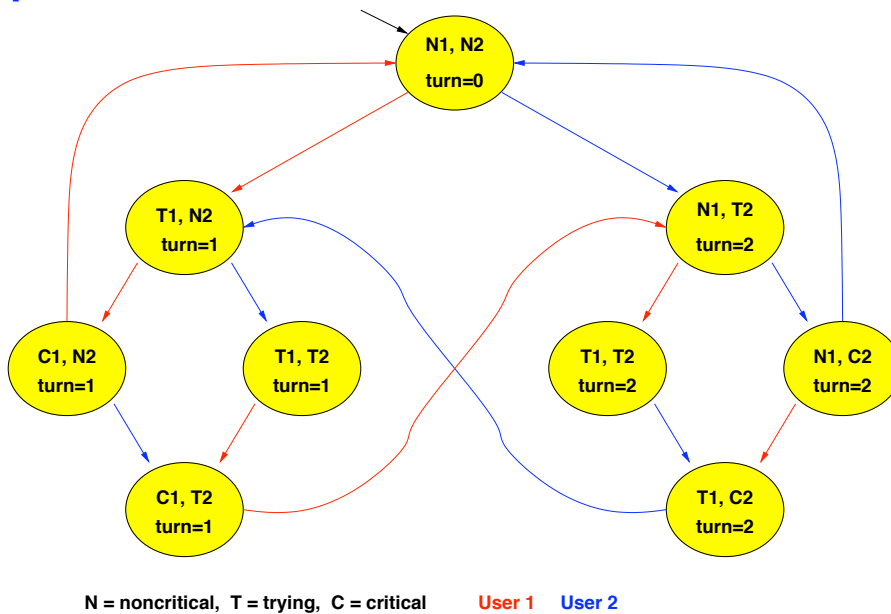
[EFEG- C_1], STEP 3



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

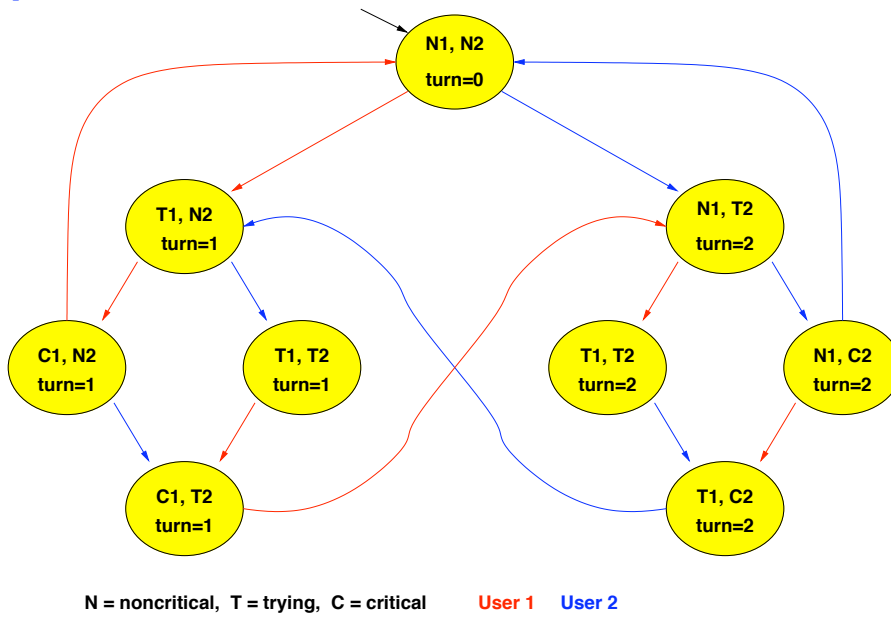
[EFEG- C_1], STEP 4



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

Example 1: fairness

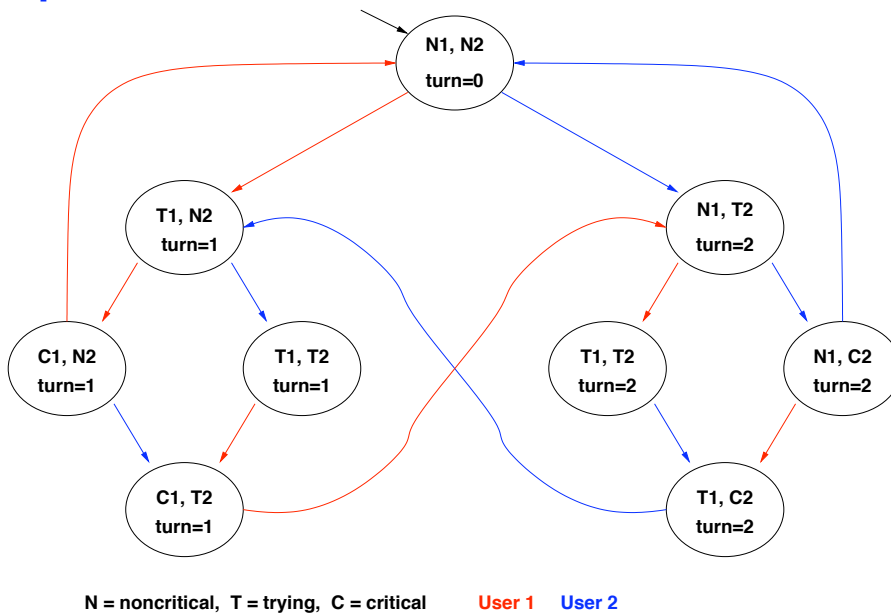
[EFEG-C₁], FIXPOINT!



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ?$$

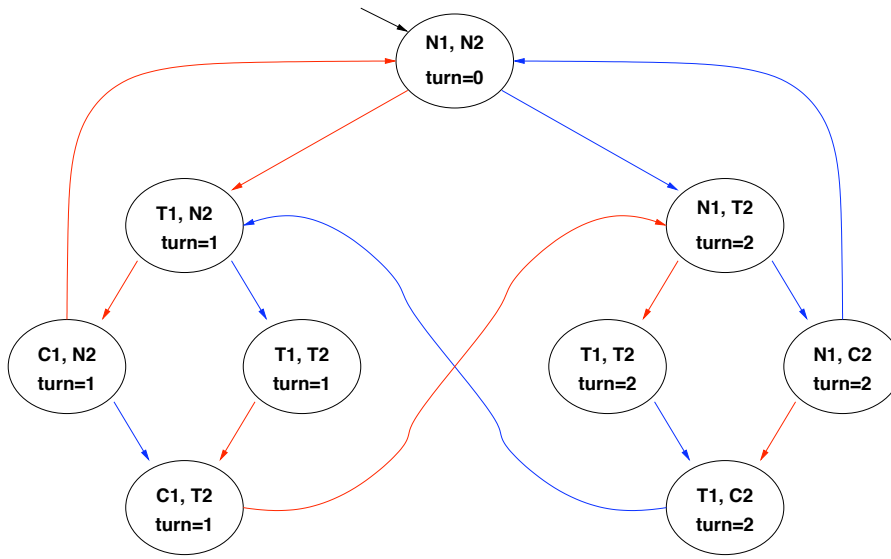
Example 1: fairness

[¬EFEG-C₁]



$$M \models \text{AGAF}C_1 ? \implies M \models \neg \text{EFEG} \neg C_1 ? \implies \text{NO!}$$

Example 2: liveness

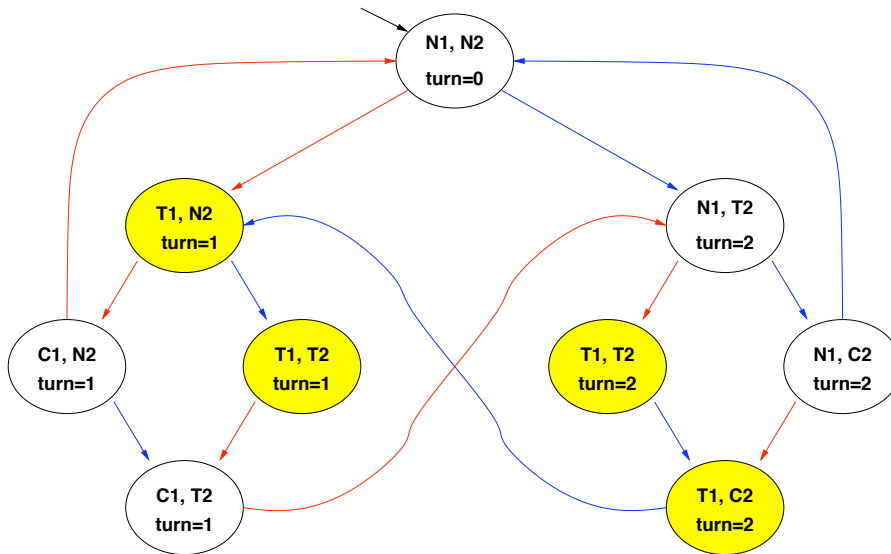


N = noncritical, T = trying, C = critical User 1 User 2

$$M \models \mathbf{AG}(T_1 \rightarrow \mathbf{AFC}_1) ? \implies M \models \neg \mathbf{EF}(T_1 \wedge \mathbf{EG} \neg C_1) ?$$

Example 2: liveness

[T₁]:

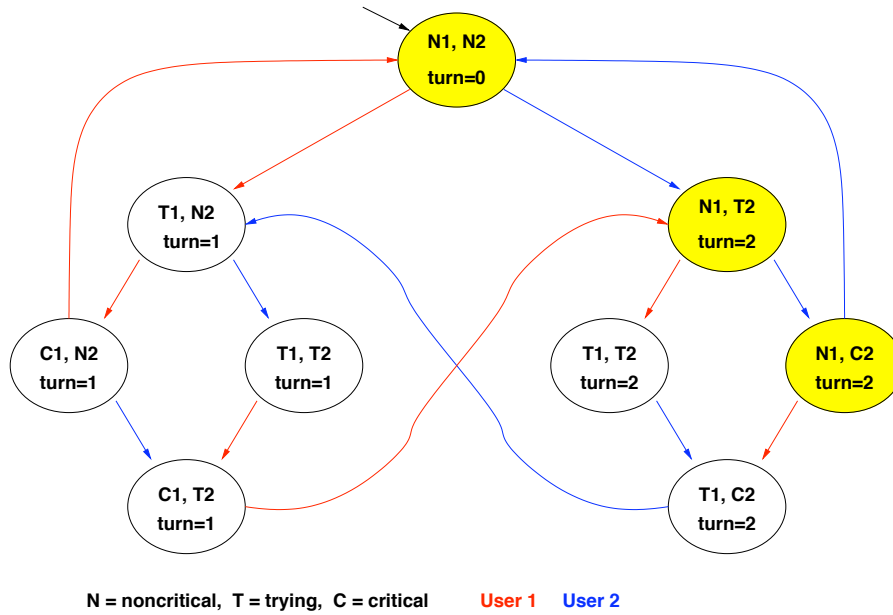


N = noncritical, T = trying, C = critical User 1 User 2

$$M \models \mathbf{AG}(T_1 \rightarrow \mathbf{AFC}_1) ? \implies M \models \neg \mathbf{EF}(T_1 \wedge \mathbf{EG} \neg C_1) ?$$

Example 2: liveness

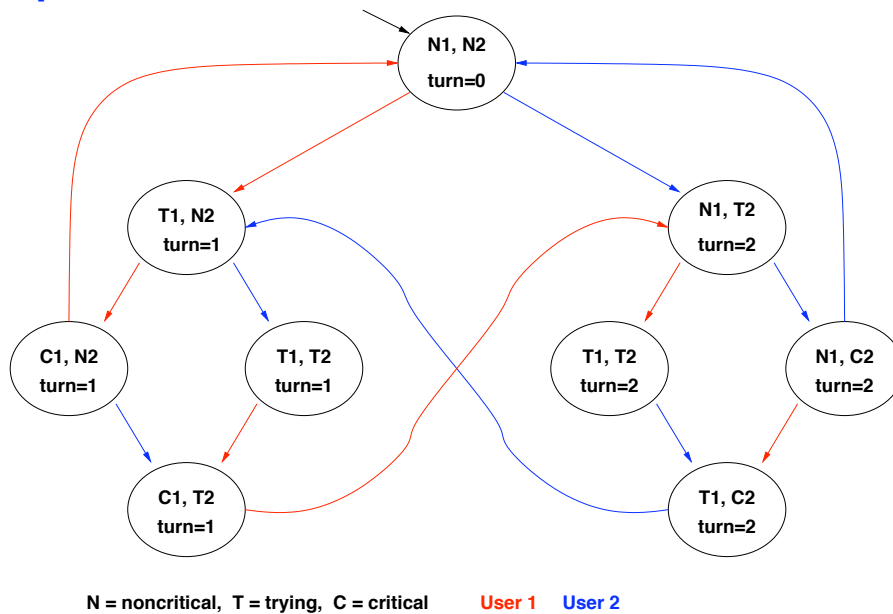
$[EG \neg C_1]$, STEPS 0-4: (see previous example)



$$M \models \mathbf{AG}(T_1 \rightarrow \mathbf{AFC}_1) ? \implies M \models \neg \mathbf{EF}(T_1 \wedge \mathbf{EG} \neg C_1) ?$$

Example 2: liveness

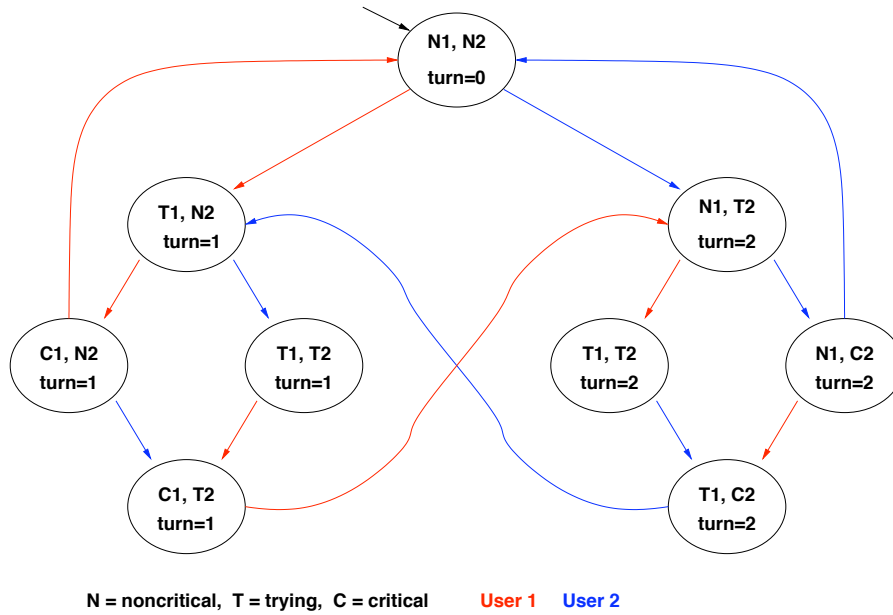
$[T_1 \wedge \mathbf{EG} \neg C_1]$:



$$M \models \mathbf{AG}(T_1 \rightarrow \mathbf{AFC}_1) ? \implies M \models \neg \mathbf{EF}(T_1 \wedge \mathbf{EG} \neg C_1) ?$$

Example 2: liveness

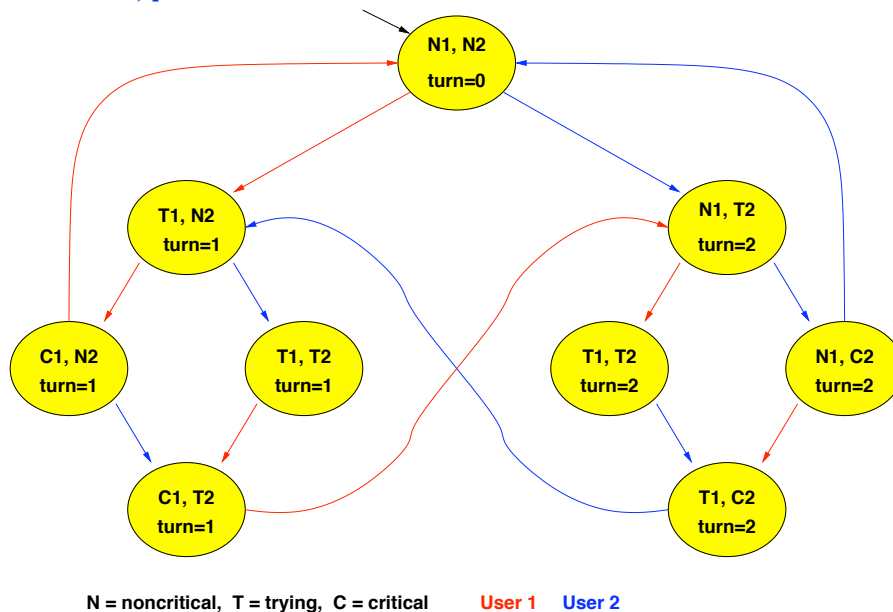
$[\mathbf{EF}(T_1 \wedge \mathbf{EG}\neg C_1)] :$



$M \models \mathbf{AG}(T_1 \rightarrow \mathbf{AFC}_1) ? \implies M \models \neg \mathbf{EF}(T_1 \wedge \mathbf{EG}\neg C_1) ?$

Example 2: liveness

$[\neg \mathbf{EF}(T_1 \wedge \mathbf{EG}\neg C_1)] :$



$M \models \mathbf{AG}(T_1 \rightarrow \mathbf{AFC}_1) ? \implies M \models \neg \mathbf{EF}(T_1 \wedge \mathbf{EG}\neg C_1) ? \text{ YES!}$