Kawasaki S030 robot workspace and data

[1] Robot Arm

<table>
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<tr>
<th>1. Model</th>
<th>RS030N-B</th>
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<tr>
<td>2. Type</td>
<td>Articulated robot</td>
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<td>3. Degree of freedom</td>
<td>6 axes</td>
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<td>4. Axis specification</td>
<td>Operating axis</td>
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<td></td>
<td>Arm rotation (JT1)</td>
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<td>Arm out-in (JT2)</td>
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<td>Arm up-down (JT3)</td>
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<td>Wrist swivel (JT4)</td>
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<td>Wrist bend (JT5)</td>
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<td>Wrist twist (JT6)</td>
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