

Master in Artificial Intelligence and Robotics (AIRO)
Electives in AI
Reasoning Agents

Fabio Patrizi

Sapienza University of Rome, Italy
patrizi@diag.uniroma1.it

A.Y. 2021-2022

CTL Model Checking*

*Slides originally by A. Artale (<https://www.inf.unibz.it/~artale/>), here restyled and modified

References:

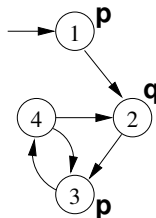
- 1 A fully detailed presentation of the topics discussed in these slides can be found in [CGP99]

- CTL Model Checking: General Ideas
- CTL Model Checking: The Labeling Algorithm
- Labeling Algorithm in Details
- CTL Model Checking: Theoretical Issues

CTL Model Checking

CTL Model Checking is an analysis technique, where:

- The world is modeled as a TS \mathcal{T} :



- The property is expressed as a CTL formula φ , e.g.:

$$\mathbf{AG}(p \rightarrow \mathbf{AF}q)$$

- The algorithm checks whether $\mathcal{T} \models \varphi$

CTL Model Checking Algorithm: General Ideas

Given \mathcal{T} and φ , the algorithm proceeds as follows:

- 1 Compute the set of states where the formula holds (called the *denotation* of φ)

$$\llbracket \varphi \rrbracket := \{s \in S : \mathcal{T}, s \models \varphi\}$$

- 2 Check whether $s_0 \in \llbracket \varphi \rrbracket$

To compute $\llbracket \varphi \rrbracket$ proceed “bottom-up” on the structure of the formula, computing $\llbracket \varphi_i \rrbracket$ for each subformula φ_i of φ .

For example, to compute $\llbracket \mathbf{AG}(p \rightarrow \mathbf{AF}q) \rrbracket$ we need to compute:

- $\llbracket q \rrbracket$,
- $\llbracket \mathbf{AF}q \rrbracket$,
- $\llbracket p \rrbracket$,
- $\llbracket p \rightarrow \mathbf{AF}q \rrbracket$,
- $\llbracket \mathbf{AG}(p \rightarrow \mathbf{AF}q) \rrbracket$

To compute each $\llbracket \phi_i \rrbracket$ for generic subformulas:

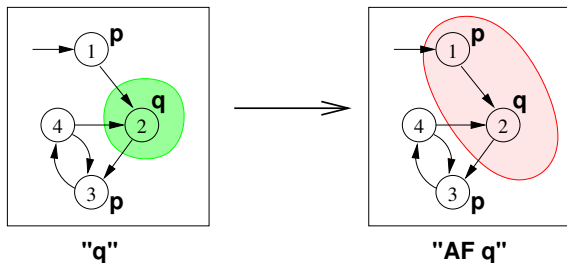
- Handle boolean operators by standard set operations;
- Handle temporal operators **AX**, **EX** by computing **pre-images**;
- Handle temporal operators **AG**, **EG**, **AF**, **EF**, **AU**, **EU**, by applying **fixpoint** operators.

- CTL Model Checking: General Ideas.
- CTL Model Checking: The Labeling Algorithm.
- Labeling Algorithm in Details.
- CTL Model Checking: Theoretical Issues.

The Labeling Algorithm: General Idea

- The **Labeling Algorithm** given a TS and a CTL formula outputs the set of states satisfying the formula.
- **Main Idea:** Label the states of the TS with the subformulas of φ satisfied there.

The Labeling Algorithm: An Example

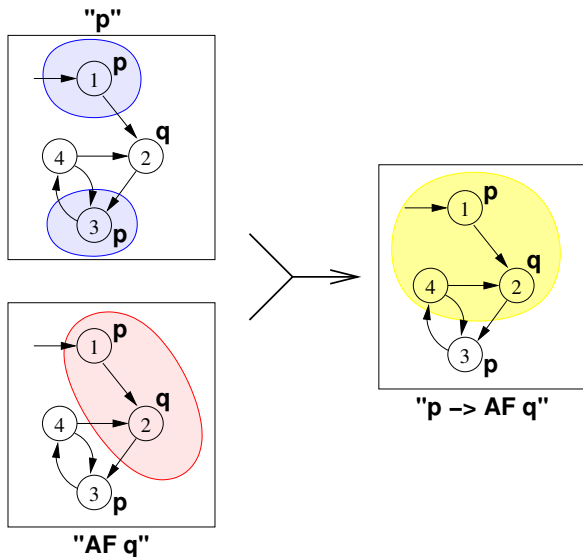


▷ $AF q \equiv (q \vee \mathbf{AX}(AF q))$

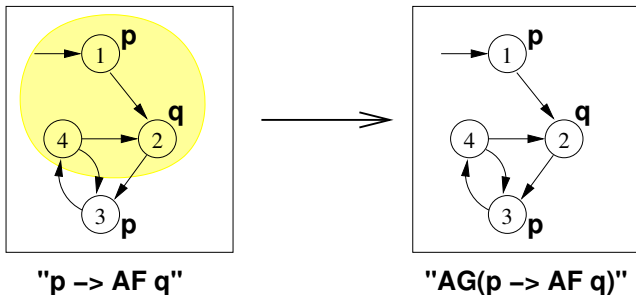
▷ $\llbracket AF q \rrbracket$ can be computed as the union of:

- $\llbracket q \rrbracket = \{2\}$
- $\llbracket q \vee \mathbf{AX} q \rrbracket = \{2\} \cup \{1\} = \{1, 2\}$
- $\llbracket q \vee \mathbf{AX}(q \vee \mathbf{AX} q) \rrbracket = \{2\} \cup \{1\} = \{1, 2\}$ (fixpoint).

The Labeling Algorithm: An Example



The Labeling Algorithm: An Example



- ▷ $AG\phi \equiv (\phi \wedge AX(AG\phi))$
- ▷ $\llbracket AG\phi \rrbracket$ can be computed as the intersection of:
 - $\llbracket \phi \rrbracket = \{1, 2, 4\}$
 - $\llbracket \phi \wedge AX\phi \rrbracket = \{1, 2, 4\} \cap \{1, 3\} = \{1\}$
 - $\llbracket \phi \wedge AX(\phi \wedge AX\phi) \rrbracket = \{1, 2, 4\} \cap \{\} = \{\}$ (fixpoint)

The Labeling Algorithm: An Example

- ▷ The set of states where the formula holds is empty, thus:
 - The initial state does not satisfy the property;
 - $\mathcal{T} \not\models \mathbf{AG}(p \rightarrow \mathbf{AF}q)$.
- ▷ **Counterexample:** A lazo-shaped path: $1, 2, \{3, 4\}^\omega$ (satisfying $\mathbf{EF}(p \wedge \mathbf{EG}\neg q)$)

- CTL Model Checking: General Ideas.
- CTL Model Checking: The Labeling Algorithm.
- [Labeling Algorithm in Details.](#)
- CTL Model Checking: Theoretical Issues.

The Labeling Algorithm: General Schema

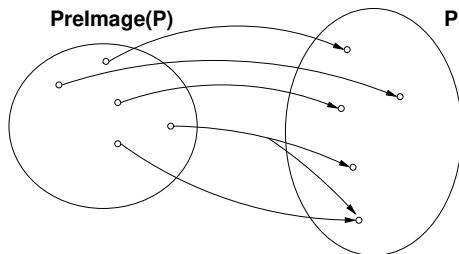
- ▷ Assume φ in terms of $\neg, \wedge, \mathbf{EX}, \mathbf{EU}, \mathbf{EG}$ (minimal set of operators)
- ▷ The Labeling algorithm takes a CTL formula and a TS as input and returns the *denotation* of φ :
 - 1 For every $\varphi_i \in \text{Sub}(\varphi)$, find $\llbracket \varphi_i \rrbracket$;
 - 2 Compute $\llbracket \varphi \rrbracket$ starting from $\llbracket \varphi_i \rrbracket$;
 - 3 Check whether $s_0 \in \llbracket \varphi \rrbracket$.
- ▷ Subformulas $\text{Sub}(\varphi)$ of φ are checked bottom-up
- ▷ To compute each $\llbracket \varphi_i \rrbracket$: if the main operator of φ_i is a
 - *Boolean Operator*: apply standard set operations;
 - *Temporal Operator*: apply recursive rules until a **fixpoint** is reached.

For a TS $\mathcal{T} = (P, A, S, s_0, \rightarrow, \lambda)$, we have:

- $\llbracket p \rrbracket = \{s \mid p \in \lambda(s)\}$ (time $O(|S|)$)
- $\llbracket \neg \varphi_1 \rrbracket = S \setminus \llbracket \varphi_1 \rrbracket$ (time $O(|S|)$)
- $\llbracket \varphi_1 \wedge \varphi_2 \rrbracket = \llbracket \varphi_1 \rrbracket \cap \llbracket \varphi_2 \rrbracket$ (time $O(|S|)$)
- Time $O(|S|)$ for all operations

Denotation of Formulas: The **EX** Case

- $\llbracket \mathbf{EX}\varphi \rrbracket = \{s \in S \mid \exists s'. s \rightarrow s' \text{ and } s' \in \llbracket \varphi \rrbracket\}$
- $\llbracket \mathbf{EX}\varphi \rrbracket$ is called the **(existential) pre-image of $\llbracket \varphi \rrbracket$** ($\text{PRE}(\llbracket \varphi \rrbracket)$)
- Key step of Labeling Algorithm



- Time $O(|\delta|) = O(|S|^2)$

- The following equivalence holds:

$$\mathbf{EG}\varphi \equiv \varphi \wedge \mathbf{EX}(\mathbf{EG}\varphi)$$

- $\llbracket \mathbf{EG}\varphi \rrbracket$ can be computed through following recursive definition:

$$\llbracket \mathbf{EG}\varphi \rrbracket = \llbracket \varphi \rrbracket \cap \text{PRE}(\llbracket \mathbf{EG}\varphi \rrbracket)$$

- Can compute $X := \llbracket \mathbf{EG}\phi \rrbracket$ as follows:
 - $X_1 := \llbracket \phi \rrbracket$
 - $X_2 := X_1 \cap \text{PRE}(X_1)$
 - \vdots
 - $X_{j+1} := X_j \cap \text{PRE}(X_j)$
 - \vdots
- When $X_n = X_{n+1}$ we reach a **fixpoint** and stop
- Since $X_{j+1} \subseteq X_j$, fixpoint exists (Tarski-Knaster theorem)
- Time: $O(|S| \cdot (|S| + |\delta|)) = O(|S|^3)$

- The following equivalence holds:

$$(\varphi \mathbf{EU} \psi) \equiv \psi \vee (\varphi \wedge \mathbf{EX}(\varphi \mathbf{EU} \psi))$$

- $\llbracket \varphi \mathbf{EU} \psi \rrbracket$ can be computed through following recursive definition:

$$\llbracket (\varphi \mathbf{EU} \psi) \rrbracket = \llbracket \psi \rrbracket \cup (\llbracket \varphi \rrbracket \cap \text{PRE}(\llbracket (\varphi \mathbf{EU} \psi) \rrbracket))$$

Denotation of Formulas: The **EU** Case

- Can compute $X := \llbracket (\varphi \mathbf{EU} \psi) \rrbracket$ as follows:
 - $X_1 := \llbracket \psi \rrbracket$
 - $X_2 := X_1 \cup (\llbracket \varphi \rrbracket \cap \text{PRE}(X_1))$
 - \vdots
 - $X_{j+1} := X_j \cup (\llbracket \varphi \rrbracket \cap \text{PRE}(X_j))$
 - \vdots
- When $X_n = X_{n+1}$ we reach a **fixpoint** and stop
- Since $X_{j+1} \supseteq X_j$, fixpoint exists (Tarski-Knaster theorem)
- Time: $O(|S| \cdot (|S| + |\delta|)) = O(|S|^3)$

The Pseudo-Code

Input:

- TS $\mathcal{T} = (P, A, S, s_0, \rightarrow, \lambda)$
- CTL formula φ

FUNCTION Label(φ) {

case φ **of**

 an atom p :

return $\{s \in S \mid p \in \lambda(s)\}$;

$\neg\varphi_1$:

return $S \setminus \text{Label}(\varphi_1)$;

$\varphi_1 \wedge \varphi_2$:

return $\text{Label}(\varphi_1) \cap \text{Label}(\varphi_2)$;

EX φ_1 :

return $\text{PRE}(\text{Label}(\varphi_1))$;

$(\varphi_1$ **EU** $\varphi_2)$:

return $\text{Label_EU}(\text{Label}(\varphi_1), \text{Label}(\varphi_2))$;

EG φ_1 :

return $\text{Label_EG}(\text{Label}(\varphi_1))$;

end case

}

$$\llbracket \mathbf{EX}\phi \rrbracket = \text{PRE}(\llbracket \phi \rrbracket) = \{s \in S \mid \exists s'. s \rightarrow s' \text{ and } s' \in \llbracket \phi \rrbracket\}$$

```
FUNCTION PRE( $\llbracket \phi \rrbracket$ ) {  
  var X;  
  X := {};  
  for each  $s' \in \llbracket \phi \rrbracket$  do  
    for each  $s \in S$  such that  $s \rightarrow s'$  do  
      X := X  $\cup$  {s};  
  return X  
}
```


$$\llbracket \mathbf{EG}\phi \rrbracket = \llbracket \phi \rrbracket \cap \text{PRE}(\llbracket \mathbf{EG}\phi \rrbracket)$$

```
FUNCTION LABEL_EG( $\llbracket \phi \rrbracket$ ) {  
  var  $X, X_{old}$ ;  
   $X := \llbracket \phi \rrbracket$ ;  
   $X_{old} := \emptyset$ ;  
  while  $X \neq X_{old}$   
  begin  
     $X_{old} := X$ ;  
     $X := X \cap \text{PRE}(X)$   
  end  
  return  $X$   
}
```

$$\llbracket (\varphi \mathbf{EU} \psi) \rrbracket = \llbracket \psi \rrbracket \cup (\llbracket \varphi \rrbracket \cap \text{PRE}(\llbracket (\varphi \mathbf{EU} \psi) \rrbracket))$$

```

FUNCTION LABEL_EU( $\llbracket \varphi \rrbracket$ ,  $\llbracket \psi \rrbracket$ ) {
  var  $X, X_{old}$ ;
   $X := \llbracket \psi \rrbracket$ ;
   $X_{old} := S$ ;
  while  $X \neq X_{old}$ 
  begin
     $X_{old} := X$ ;
     $X := X \cup (\llbracket \varphi \rrbracket \cap \text{PRE}(X))$ 
  end
  return  $X$ 
}

```

- CTL Model Checking: General Ideas.
- CTL Model Checking: The Labeling Algorithm.
- Labeling Algorithm in Details.
- CTL Model Checking: Theoretical Issues.

- The Labeling Algorithm proceeds recursively on the structure of φ
- For the Boolean and **EX** operators, termination and correctness follow from semantics
- Need to prove correctness and termination for **EG** and **EU** operators

Definition (Monotone Function)

Let S be a set and $F : 2^S \rightarrow 2^S$ a function

- 1 F is *monotone* if $X \subseteq Y$ implies $F(X) \subseteq F(Y)$
- 2 A set $X \subseteq S$ s.t. $F(X) = X$ of S is called a *fixpoint* of F
- 3 $X \subseteq S$ is a *least fixpoint* (LFP) of F , written $X = \mu X.F(X)$, if, for every other fixpoint Y of F , $X \subseteq Y$
- 4 $X \subseteq S$ is a *greatest fixpoint* (GFP) of F , written $X = \nu X.F(X)$, if, for every other fixpoint Y of F , $Y \subseteq X$

Example. Let $S = \{s_0, s_1\}$ and $F(X) = X \cup \{s_0\}$.

Notation: $F^i(X)$ means applying F i -times, i.e., $F(F(\dots F(X)\dots))$.

Theorem (Tarski-Knaster '55)

If $F : 2^S \rightarrow 2^S$ is a monotone function, over finite S s.t. $|S| = n$, then:

- 1 $\mu X.F(X) \equiv F^n(\emptyset)$
- 2 $\nu X.F(X) \equiv F^n(S)$

The function LABEL_EG computes:

$$\llbracket \mathbf{EG}\varphi \rrbracket = \llbracket \varphi \rrbracket \cap \text{PRE}(\llbracket \mathbf{EG}\varphi \rrbracket)$$

applying the semantic equivalence:

$$\mathbf{EG}\varphi \equiv \varphi \wedge \mathbf{EX}(\mathbf{EG}\varphi)$$

$\llbracket \mathbf{EG}\varphi \rrbracket$ is the **fixpoint** of the function:

$$F(X) = \llbracket \varphi \rrbracket \cap \text{PRE}(X)$$

Theorem

Let $F(X) = \llbracket \varphi \rrbracket \cap \text{PRE}(X)$, with $X \subseteq S$ and $|S| = n$. Then:

- 1 F is monotone;
- 2 $\llbracket \mathbf{EG}\varphi \rrbracket$ is the *greatest fixpoint* of F .

The function LABEL_EU computes:

$$\llbracket (\varphi \mathbf{EU} \psi) \rrbracket = \llbracket \psi \rrbracket \cup (\llbracket \varphi \rrbracket \cap \text{PRE}(\llbracket (\varphi \mathbf{EU} \psi) \rrbracket))$$

applying the semantic equivalence:

$$(\varphi \mathbf{EU} \psi) \equiv \psi \vee (\varphi \wedge \mathbf{EX}(\varphi \mathbf{EU} \psi))$$

$\llbracket (\varphi \mathbf{EU} \psi) \rrbracket$ is the **fixpoint** of the function:

$$F(X) = \llbracket \psi \rrbracket \cup (\llbracket \varphi \rrbracket \cap \text{PRE}(X))$$

Theorem

Let $F(X) = \llbracket \psi \rrbracket \cup (\llbracket \varphi \rrbracket \cap \text{PRE}(X))$, with $X \subseteq S$ and $|S| = n$. Then:

- 1 F is monotone;
- 2 $\llbracket (\varphi \mathbf{EU} \psi) \rrbracket$ is the *least fixpoint* of F .

Complexity of CTL Model Checking

- The Labeling Algorithm operates in time: $O(|\varphi| \cdot |S| \cdot (|S| + |\delta|))$
- Since $|\delta| = O(|S|^2)$, we have:

$$O(|\varphi| \cdot |S|^3)$$

- Can be further optimized to:

$$O(|\varphi| \cdot |S|^2)$$

Theorem

CTL Model Checking can be solved in polynomial time wrt $|\varphi| + |S|$

-  Edmund M Clarke, Orna Grumberg, and Doron A. Peled.
Model checking.
MIT Press, London, Cambridge, 1999.