

# AMR 2014/2015: Final Project Assignments

**FP1. Task control of a nonholonomic mobile manipulator (shared with Rob 2)**  
Maurizio Maisto, Massimiliano Mancini, Federica Scazzola

**FP4. Humanoid walking motion generation: preview control schemes**  
Andrea Di Maria, Fulvio Di Profio, Raffaele Palamides

**FP6. Generating reaching motions for a humanoid**  
José Luis Bustamante Julca, Alessandra Ciorra

**FP10. Planning transfers between equilibria for a quadrotor**  
Valerio Costantini, Adriano Pallotta, Marco Presciuttini

**FP11. Implementation of feedback controllers for unicycle robots**  
Mirco Colosi, Andrea Gigli, Sidali Rezetane