

# AMR 2013/2014: Final Project Assignments

## FP2: Elastic strips

Lacagnina, Muscio, Versace

Lab supervisor: Marco Cagnetti

## FP4: On-line replanning for humanoid robots

Perusini, Sanelli, Spada

Lab supervisor: Marco Cagnetti

## FP5: Path planning among movable obstacles

Imperoli, Mattioli, Washaha

Lab supervisor: Marilena Vendittelli

## FP6: Humanoid walking motion generation: A comparison

Finzi, Okoya, Pivsaev

Lab supervisor: Leonardo Lanari

## FP7: Robot motion planning with soft task constraints

Catalano, Ferrari, Rocco

Lab supervisor: Massimo Cefalo

## FP8: Manipulation planning with soft task constraints

Al Khudir, Liatis, Stella

Lab supervisor: Massimo Cefalo

## FP10: Eulerian Video Magnification

Cifanelli, Grazioso, Tammaro

Lab supervisor: Valerio Modugno

## FP11: Quadrotor dynamic modeling and motion planning in V-REP

Baldini, Cruciani, Palazzolo

Lab supervisor: Massimo Cefalo

## Notes:

- names in magenta were assigned ex officio by me to complete groups
- names in blue: project is not valid for final grade