

# Model checking with Interval Temporal Logic: Results and Perspectives

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# Model checking

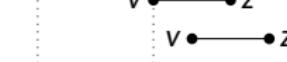
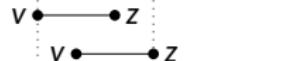
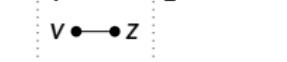
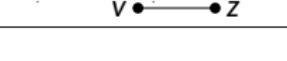
- **Model checking** (MC): the desired properties of a system are checked against a model of the system, where
  - the **model** is a (finite) state-transition graph
  - system properties are specified by a **temporal logic** (LTL, CTL, CTL\*, and the like)
- Distinctive features of MC:
  - **exhaustive** verification of all the possible behaviours
  - **fully automatic** process
  - a **counterexample** is produced for a violated property

# Point-based vs. interval-based MC

- MC is usually **point-based**:
  - properties express requirements over points (snapshots) of a computation (states of the state-transition system)
  - they are specified by means of point-based temporal logics such as LTL, CTL, and CTL\*.
- **Interval-based** MC:
  - interval-based properties express conditions on **computation stretches**
  - they are specified by means of **interval temporal logics**, which feature intervals as their basic ontological entities
    - » ability to express, for instance, **actions with duration, accomplishments, aggregations**
    - » applications in the areas of computational linguistics, artificial intelligence, temporal databases, formal verification, etc.

# The logic HS

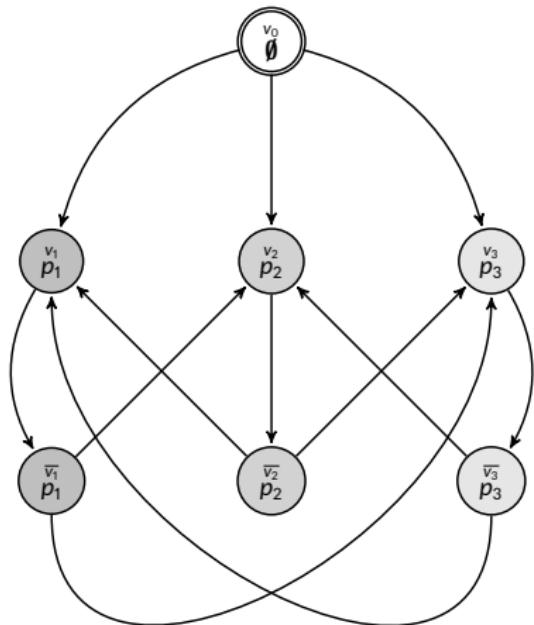
HS features a modality for each of the 13 Allen's ordering relations between pairs of intervals (except for equality)

Allen rel.	HS	Definition	Example
meets	$\langle A \rangle$	$[x, y] \mathcal{R}_A [v, z] \iff y = v$	
before	$\langle L \rangle$	$[x, y] \mathcal{R}_L [v, z] \iff y < v$	
started-by	$\langle B \rangle$	$[x, y] \mathcal{R}_B [v, z] \iff x = v \wedge z < y$	
finished-by	$\langle E \rangle$	$[x, y] \mathcal{R}_E [v, z] \iff y = z \wedge x < v$	
contains	$\langle D \rangle$	$[x, y] \mathcal{R}_D [v, z] \iff x < v \wedge z < y$	
overlaps	$\langle O \rangle$	$[x, y] \mathcal{R}_O [v, z] \iff x < v < y < z$	

$$\psi ::= p \mid \neg \psi \mid \psi \vee \psi \mid \langle X \rangle \psi \mid \langle \bar{X} \rangle \psi \quad X \in \{A, L, B, E, D, O\}.$$

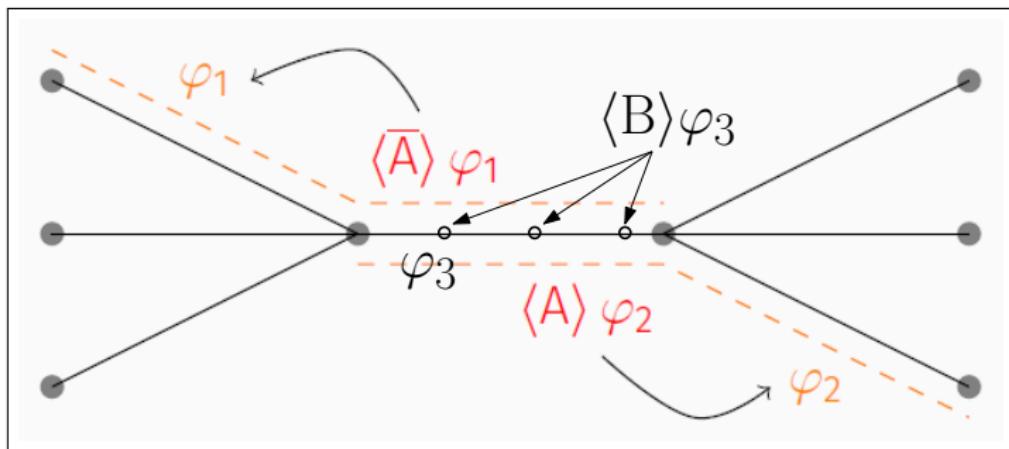
All modalities can be expressed by means of  $\langle A \rangle$ ,  $\langle B \rangle$ ,  $\langle E \rangle$  and their transposed modalities  $\langle \bar{A} \rangle$ ,  $\langle \bar{B} \rangle$ ,  $\langle \bar{E} \rangle$  only

## Kripke structures



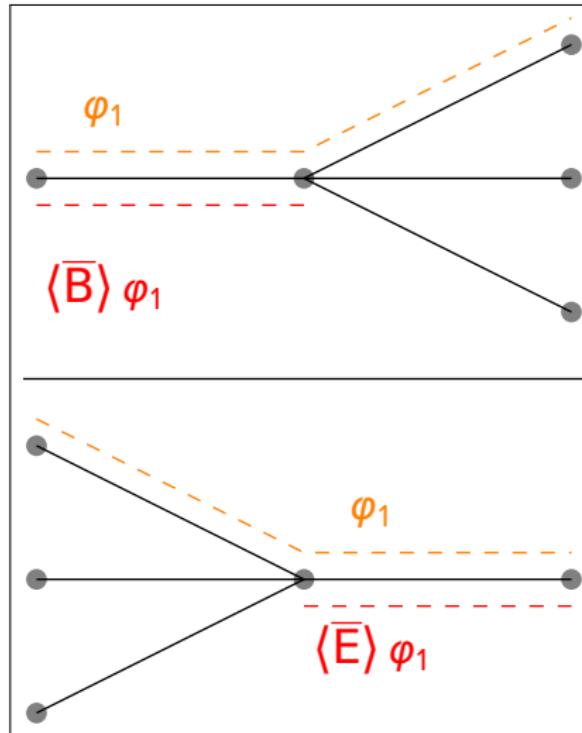
- HS formulas are interpreted over (finite) state-transition systems whose states are labeled with sets of proposition letters (**Kripke structures**)
- An interval is a **trace** (finite path) in a Kripke structure

## HS (state-based) semantics



- Branching semantics of past/future operators

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## HS (state-based) semantics and MC

Truth of a formula  $\psi$  over a trace  $\rho$  of a Kripke structure:

- $\rho$  models  $p \Leftrightarrow p$  labels **all** states of  $\rho$ , for any letter  $p \in \mathcal{AP}$  (**homogeneity assumption**);

## HS (state-based) semantics and MC

Truth of a formula  $\psi$  over a trace  $\rho$  of a Kripke structure:

- $\rho$  models  $p \Leftrightarrow p \in \mu(\text{fst}(\rho), \text{lst}(\rho))$ , for any letter  $p \in \mathcal{AP}$   
**(endpoint-based labeling);**

## HS (state-based) semantics and MC

Truth of a formula  $\psi$  over a trace  $\rho$  of a Kripke structure:

- $\rho$  models  $r \Leftrightarrow \mu(\rho) \in \mathcal{L}(r)$   
(labeling based on regular expressions, subsuming the others);

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- $\rho$  models  $r \Leftrightarrow \mu(\rho) \in \mathcal{L}(r)$   
(labeling based on regular expressions, subsuming the others);
- negation, disjunction, and conjunction are standard;
- $\mathcal{K} \rho \models \langle A \rangle \psi \dots$ ;
- $\mathcal{K} \rho \models \langle B \rangle \psi \dots$ ;
- $\mathcal{K} \rho \models \langle E \rangle \psi \dots$ ;
- inverse operators  $\langle \bar{A} \rangle, \langle \bar{B} \rangle, \langle \bar{E} \rangle$

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## MC

$\mathcal{K} \models \psi \Leftrightarrow$  all initial traces of  $\mathcal{K}$  model  $\psi$

Possibly infinitely many traces!

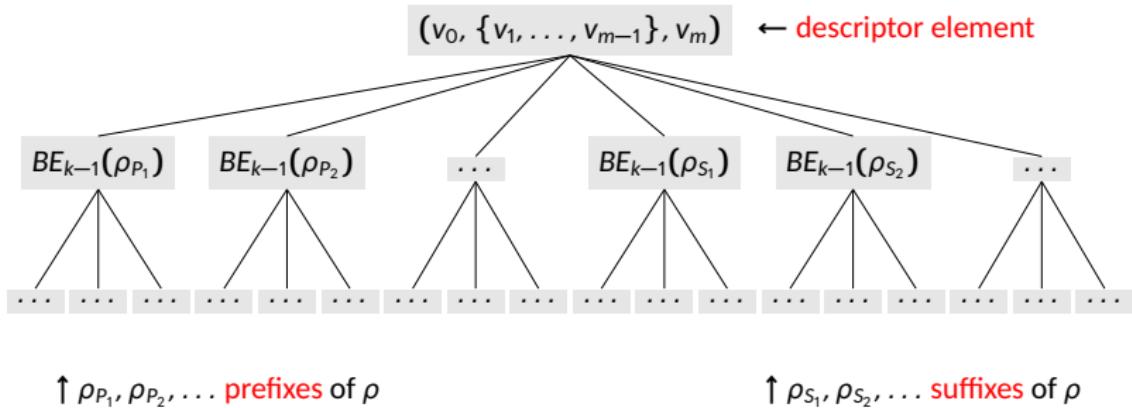
## MC: the key notion of $BE_k$ -descriptor

- The **BE-nesting depth** of an HS formula  $\psi$  ( $\text{Nest}_{\text{BE}}(\psi)$ ) is the maximum degree of nesting of modalities  $B$  and  $E$  in  $\psi$
- Two traces  $\rho$  and  $\rho'$  of a Kripke structure  $\mathcal{K}$  are  **$k$ -equivalent** iff:  
 $\mathcal{K}, \rho \models \psi$  iff  $\mathcal{K}, \rho' \models \psi$  for all HS formulas  $\psi$  with  $\text{Nest}_{\text{BE}}(\psi) \leq k$

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For any given  $k$ , we provide a suitable tree representation for a trace, called a  $BE_k$ -descriptor: the  **$BE_k$ -descriptor**  $BE_k(\rho)$  for a trace  $\rho = v_0 v_1 \dots v_{m-1} v_m$  has the following structure:

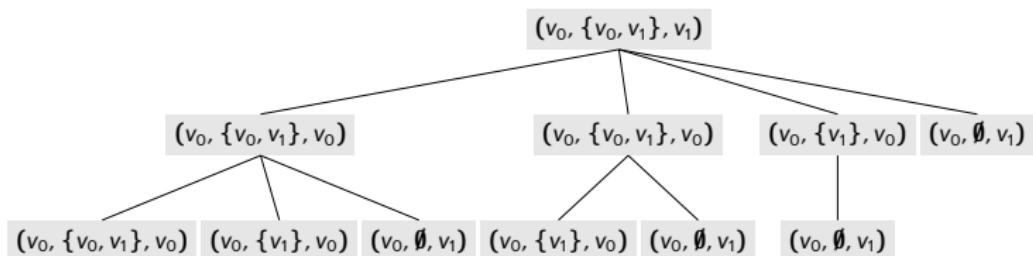


**Remark:** the descriptor does not feature sibling isomorphic subtrees

## An example of a $BE_2$ -descriptor



The  $BE_2$ -descriptor for the trace  $\rho = v_0v_1v_0^4v_1$  (for the sake of readability, only the subtrees for prefixes are displayed and point intervals are excluded)



**Remark:** the subtree to the left is associated with both prefixes  $v_0v_1v_0^3$  and  $v_0v_1v_0^4$  (no sibling isomorphic subtrees in the descriptor)

## Two basic facts

### FACT 1

For any Kripke structure  $\mathcal{K}$  and any BE-nesting depth  $k \geq 0$ , the number of different  $BE_k$ -descriptors is **finite** (and thus at least one descriptor has to be associated with infinitely many traces)

### FACT 2

Two traces  $\rho$  and  $\rho'$  of a Kripke structure  $\mathcal{K}$  described by the **same**  $BE_k$ -descriptor are ***k*-equivalent**

# Decidability of the MC problem for HS

## Theorem

The MC problem for full HS over Kripke structures, **under homogeneity**, is decidable (with a non-elementary algorithm)

## Reference

A. Molinari, A. Montanari, A. Murano, G. Perelli, and A. Peron. Checking interval properties of computations.

*Acta Informatica*, pages 587–619, 2016

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## Theorem

The MC problem for full HS **with regular expressions** over Kripke structures is decidable (with a non-elementary algorithm)

## Reference

L. Bozzelli, A. Molinari, A. Montanari, and A. Peron. Model checking interval temporal logics with regular expressions.

*Information and Computation*, 2018

## What about the lower bound?

EXPSPACE-hardness of BE: a polynomial-time reduction from a domino-tiling problem for grids with rows of single exponential length

### Theorem

*The MC problem for BE over Kripke structures (under homogeneity/with regular expressions) is EXPSPACE-hard.*

### Reference

L. Bozzelli, A. Molinari, A. Montanari, A. Peron, and P. Sala. Which fragments of the interval temporal logic HS are tractable in model checking?

*Theoretical Computer Science*, 2018

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*Theoretical Computer Science*, 2018

The exact complexity of MC for BE is a difficult problem we are working on (BE is strictly in between Venema's CDT and the logic D of the sub-interval relation)

## The MC problem for HS fragments: the logic $\overline{A\overline{A}B\overline{B}E}$

Let us consider the case of the logic  $\overline{A\overline{A}B\overline{B}E}$ , which is obtained from full HS  $(A\overline{A}B\overline{B}E)$  by removing modality  $\langle E \rangle$

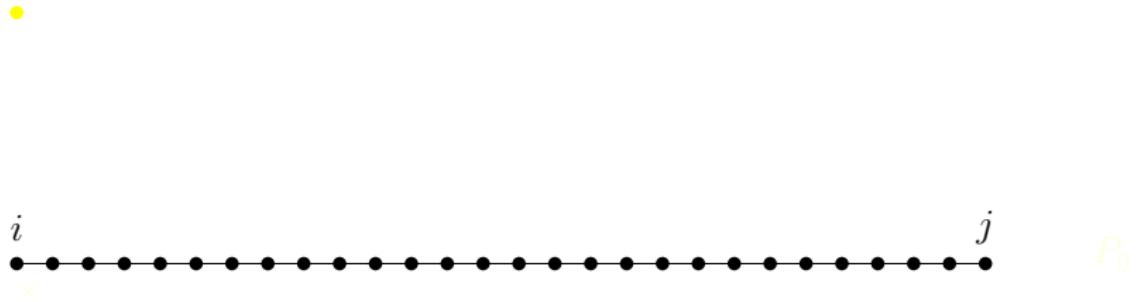
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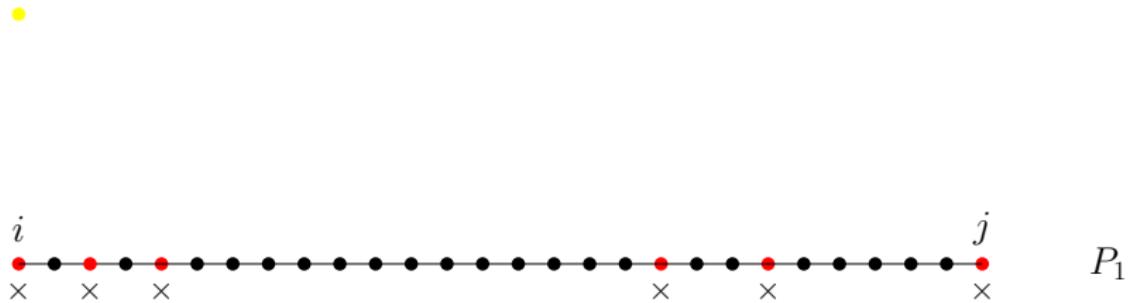
A high-level account of the solution:

- we can restrict our attention to **prefixes** ( $B_k$ -descriptors suffice)
- the size of the tree representation of  $B_k$ -descriptors is larger than necessary (**redundancy**) and it prevents their efficient use in MC algorithms
- a **trace representative** can be chosen to represent a (possibly infinite) set of traces associated with the same  $B_k$ -descriptor
- a **bound**, which depends on both the number  $|W|$  of states of the Kripke structure and the B-nesting depth  $h$  of the formula to check, can be given to the length of trace representatives

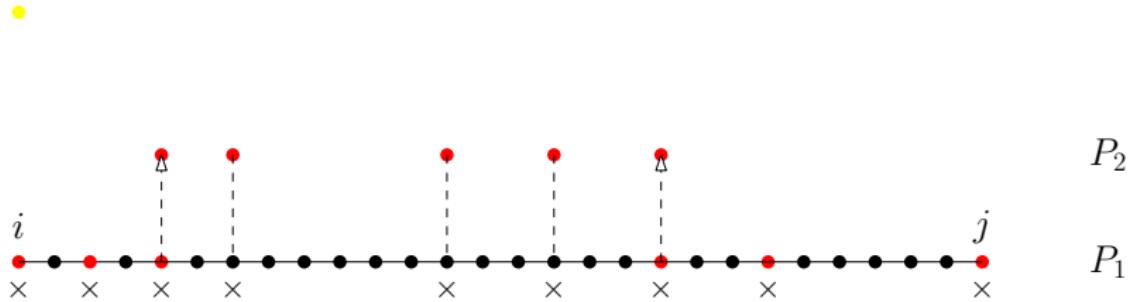
## The basic idea: $h$ -prefix sampling



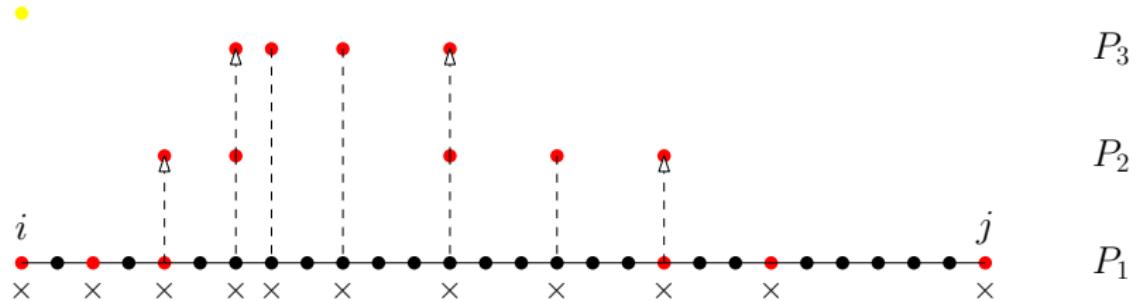
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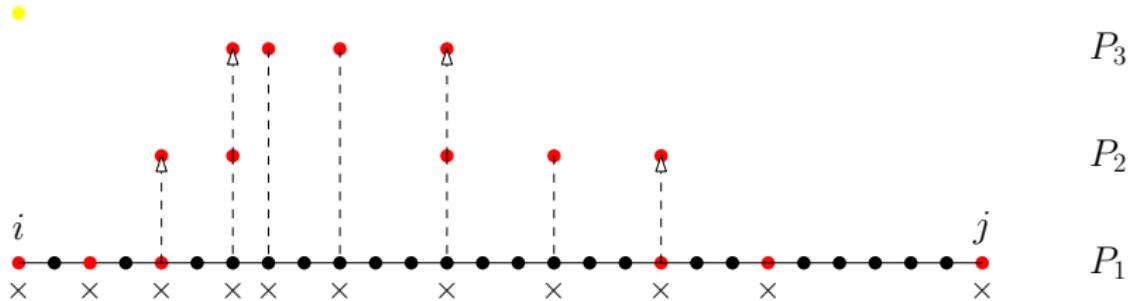
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### Proposition

The  $h$ -prefix sampling  $P_h$  of (any) trace  $\rho$  is such that  $|P_h| \leq (|W| + 2)^h$ .

# An EXPSPACE MC algorithm for A $\overline{A}$ B $\overline{B}$ E

## Theorem (Small model/trace property)

Given a trace  $\rho$ , we can derive its trace representative  $\rho'$ ,  
Nest<sub>B</sub>( $\psi$ )-equivalent to it, such that  $|\rho'| \leq (|W| + 2)^{\text{Nest}_B(\psi) + 2}$

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### Algorithm 1 ModCheck( $\mathcal{K}, \psi$ )

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```
1:  $h \leftarrow \text{Nest}_B(\psi)$ 
2: for all initial traces  $\rho'$  with  $|\rho'| \leq (|W| + 2)^{h+2}$  do
3:   if Check( $\mathcal{K}, h, \psi, \rho'$ ) = 0 then return 0: " $\mathcal{K}, \rho' \not\models \psi$ "  $\triangleleft$  Counterex X
   return 1: " $\mathcal{K} \models \psi$ "  $\triangleleft$  MC OK ✓
```

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## Reference

L. Bozzelli, A. Molinari, A. Montanari, A. Peron, and P. Sala. Which fragments of the interval temporal logic HS are tractable in model checking?

Theoretical Computer Science, 2018

# Complexity results

	Homogeneity
Full HS, BE	non-elementary <b>EXPSPACE</b> -hard
$\overline{AABBE}$ , $\overline{AAEBE}$	$\in \mathbf{AEXP}_{\text{Pol}}$ <b>PSPACE</b> -hard
$\overline{AABE}$	<b>PSPACE</b> -complete
$\overline{AABB}$ , $\overline{BB}$ , $\overline{B}$ , $\overline{AAEE}$ , $\overline{EE}$ , $\overline{E}$	<b>PSPACE</b> -complete
$\overline{AAB}$ , $\overline{AAE}$ , $AB$ , $\overline{AE}$	<b>P<sup>NP</sup></b> -complete
$\overline{AA}$ , $\overline{AB}$ , $AE$ , $A$ , $\overline{A}$	$\in \mathbf{P}^{\mathbf{NP}}[\mathcal{O}(\log^2 n)]$ <b>P<sup>NP</sup>[<math>\mathcal{O}(\log n)</math>]</b> -hard
Prop, B, E	<b>co-NP</b> -complete

# Complexity results

	Homogeneity	Regular expressions
Full HS, BE	non-elementary EXPSPACE-hard	non-elementary EXPSPACE-hard
A $\bar{A}$ B $\bar{B}$ E, A $\bar{A}$ E $\bar{B}$ E	$\in \text{AEXP}_{\text{Pol}}$ PSPACE-hard	$\text{AEXP}_{\text{Pol}}$ -complete
A $\bar{A}$ B $\bar{E}$	PSPACE-complete	$\in \text{AEXP}_{\text{Pol}}$ PSPACE-hard
A $\bar{A}$ B $\bar{B}$ , B $\bar{B}$ , $\bar{B}$ , A $\bar{A}$ E $\bar{E}$ , E $\bar{E}$ , $\bar{E}$	PSPACE-complete	PSPACE-complete
A $\bar{A}$ B, A $\bar{A}$ E, AB, $\bar{A}$ E	$\text{P}^{\text{NP}}$ -complete	PSPACE-complete
A $\bar{A}$ , $\bar{A}$ B, AE, A, $\bar{A}$	$\in \text{P}^{\text{NP}}[O(\log^2 n)]$ $\text{P}^{\text{NP}}[O(\log n)]$ -hard	PSPACE-complete
Prop, B, E	co-NP-complete	PSPACE-complete

# Complexity results

## Reference

A. Molinari, A. Montanari, and A. Peron. Model checking for fragments of halpern and shoham's interval temporal logic based on track representatives.

*Information and Computation*, 259:412–443, 2018

## Reference

L. Bozzelli, A. Molinari, A. Montanari, A. Peron, and P. Sala. Which fragments of the interval temporal logic HS are tractable in model checking?

*Theoretical Computer Science*, 2018

## Reference

L. Bozzelli, A. Molinari, A. Montanari, A. Peron, and P. Sala. Model checking for fragments of the interval temporal logic HS at the low levels of the polynomial time hierarchy.

*Information and Computation*, 262:241–264, 2018

## Point vs. interval temporal logic MC

**Question:** is there any advantage in replacing points by intervals as the primary temporal entities, or is it just a matter of taste?

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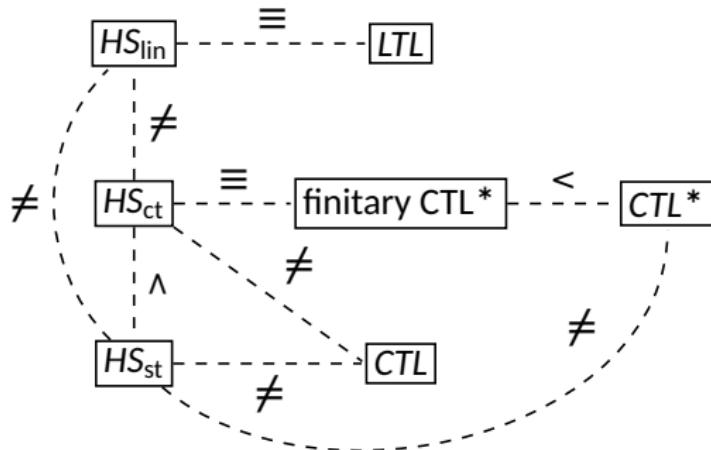
**Question:** is there any advantage in replacing points by intervals as the primary temporal entities, or is it just a matter of taste?

In order to compare the **expressiveness** of HS in MC with that of LTL, CTL, and CTL\*, we consider three semantic variants of HS:

- HS with state-based semantics (the original one);
- HS with computation-tree-based semantics;
- HS with trace-based semantics.

These variants are compared with the above standard temporal logics and among themselves.

## Expressiveness results (under homogeneity)



### Reference

L. Bozzelli, A. Molinari, A. Montanari, A. Peron, and P. Sala. Interval vs. point temporal logic model checking: an expressiveness comparison.  
*ACM Transactions on Computational Logic*, 2018

## Towards more general system models

We are looking for possible **replacements** of **Kripke structures** by more expressive system models:

- **interval-based system models**, that allow one to directly describe systems on the basis of their interval behavior/properties (e.g., **timelines**).
- **visibly pushdown systems**, that can encode recursive programs and infinite state systems;

### Reference

L. Bozzelli, A. Molinari, A. Montanari, and A. Peron. Decidability and Complexity of Timeline-based Planning over Dense Temporal Domains. In *KR*, 2018

### Reference

L. Bozzelli, A. Molinari, A. Montanari, and A. Peron. Complexity of timeline-based planning over dense temporal domains: exploring the middle ground.

In *GandALF*, 2018