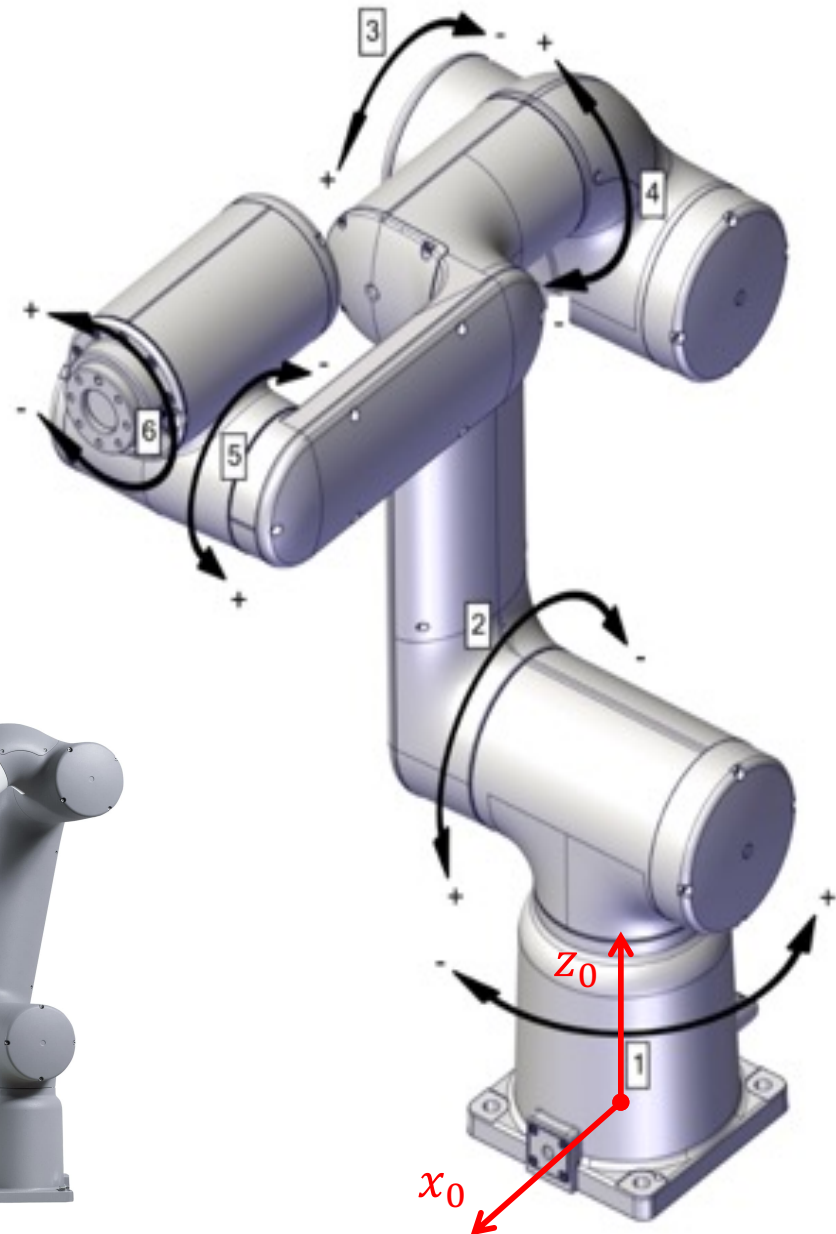
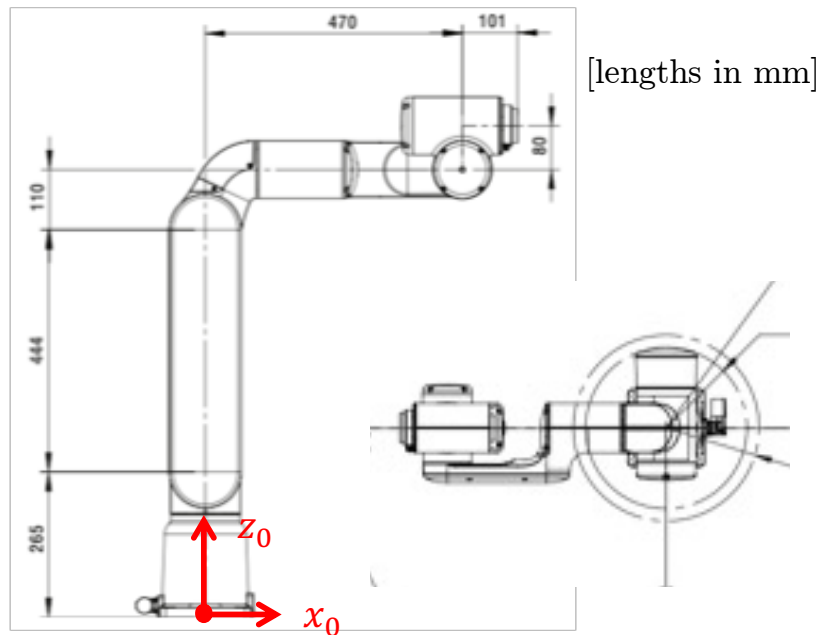


DH frames assignment and table for the ABB CRB 15000 (GoFa) robot

i	α_i	a_i	d_i	θ_i
1				
2				
3				
4				
5				
6				



left side view

top view

right side view