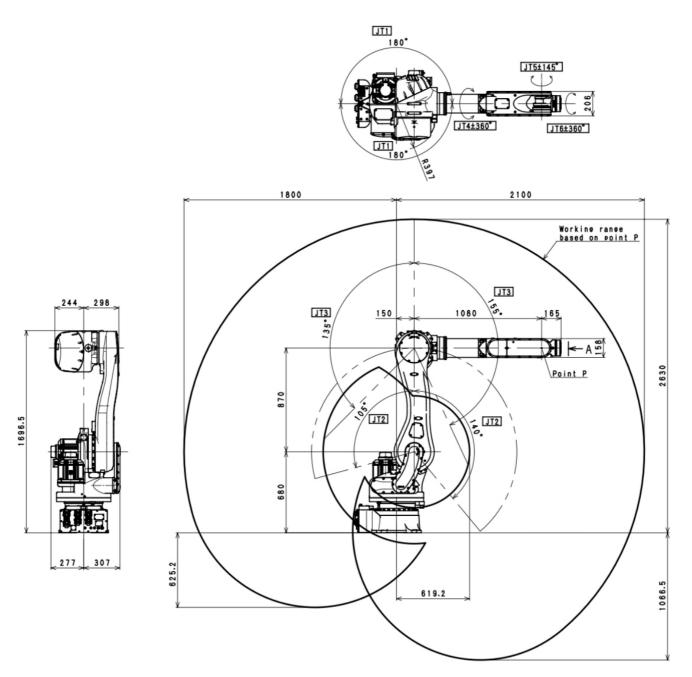
## Robotics I – Data sheet June 17, 2019

Kawasaki S030 robot workspace and data



[1] Robot Arm				
1. Model	RS030N-B			
2. Туре	Articulated robot			
3. Degree of freedom	6 axes			
4. Axis specification	Operating axis		Max. operating range	Max. speed
	Arm rotation	(JT1)	+180 $^{\circ}\sim$ -180 $^{\circ}$	180 °/s
	Arm out-in	(JT2)	+140 $^{\circ}\sim$ $-105$ $^{\circ}$	180 °/s
	Arm up-down	(JT3)	+135 $^{\circ}\sim$ -155 $^{\circ}$	185 °/s
	Wrist swivel	(JT4)	$+360~^\circ\sim\!-360~^\circ$	260 °/s
	Wrist bend	(JT5)	$+145~^\circ\sim\!-145~^\circ$	260 °/s
	Wrist twist	(JT6)	$+360~\degree\sim\!-360~\degree$	360 °/s