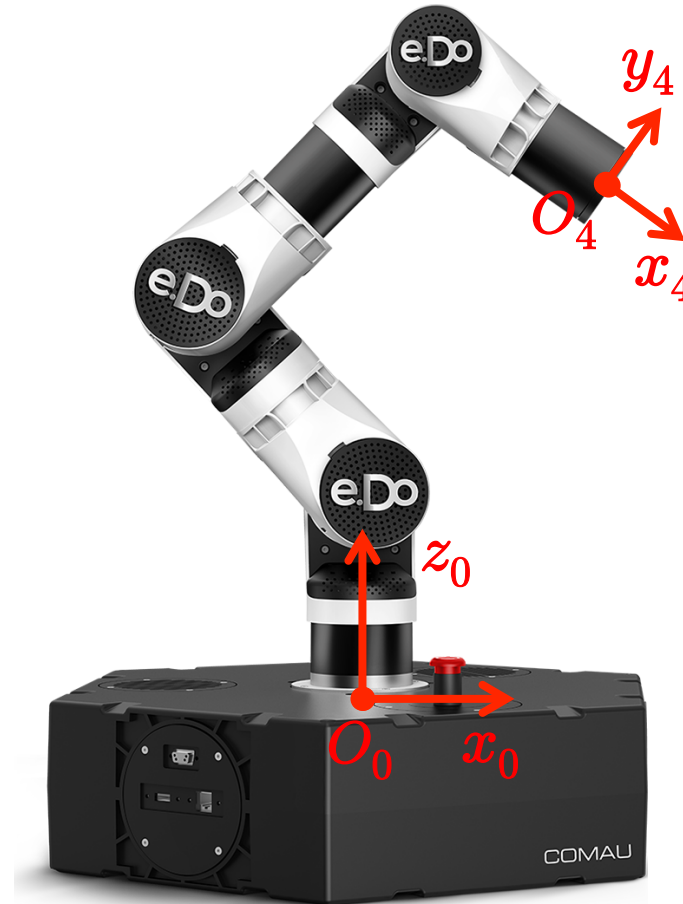
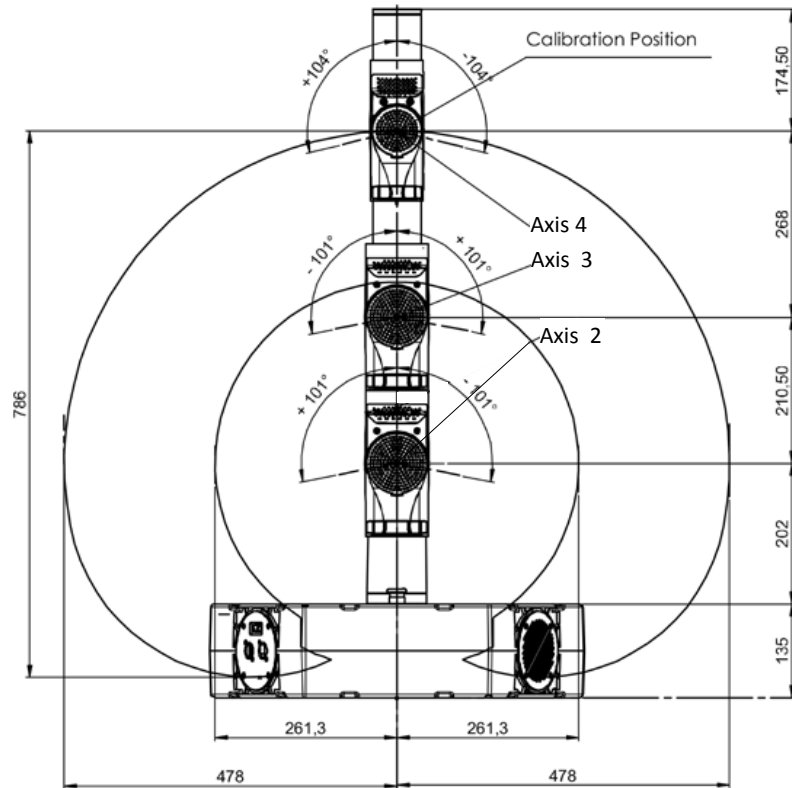


4R e.Do robot by Comau – DH frames assignment and table

Name: _____



i	α_i	a_i	d_i	θ_i
1				
2				
3				
4				

all **constant** DH parameters should be ≥ 0