



IEEE ROBOTICS AND AUTOMATION SOCIETY

Best Conference Paper Award - Finalist

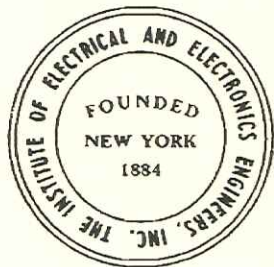
IEEE International Conference on Robotics and Automation – ICRA 2015
26-30 May 2015 – Seattle, WA USA

is presented to

Alessandro De Luca

for the paper entitled

*“Control of Generalized Contact Motion and
Force in Physical Human-Robot Interaction”*



A handwritten signature in black ink, appearing to read "Lynne E. Parker".

Lynne E. Parker
General Chair, ICRA 2015

A handwritten signature in black ink, appearing to read "Lydia Kavraki".

Lydia Kavraki
Awards Chair, ICRA 2015



28 May 2015