

Structural Operational Semantics of Program

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Programs

We will consider a very simple programming language that we call “**while**”.

while-programs

a	atomic action
$skip$	empty action
$\delta_1; \delta_2$	sequence
if ϕ then δ_1 else δ_2	if-then-else
while ϕ do δ	while-loop

As atomic action we will typically consider assignments:

$$x := v$$

As test any boolean condition on the current state of the memory.

Note that our considerations extend to full-fledged programming language (as Java).

Program semantics

Programs are syntactic objects.

How do we assign a formal semantics to them?

Any idea of what the semantics should talk about?

Evaluation semantics

Idea: describe the overall result of the evaluation of the program.

Evaluation semantics

Given a program δ and a memory state s **compute the memory state s' obtained by executing δ in s .**

More formally: define the **relation**:

$$(\delta, s) \longrightarrow s'$$

where δ is a program, s is the memory state in which the program is evaluated, and s' is the memory state obtained by the evaluation.

Such a relation can be defined inductively in a standard way using the so called **evaluation (structural) rules**

Evaluation semantics: references

The general approach we follow is the *structural operational semantics* approach [Plotkin81, Nielson&Nielson99].

This whole-computation semantics is often called: *evaluation semantics* or *natural semantics* or *computation semantic*.

Evaluation rules for **while**-programs

Evaluation rules for **while**-programs

$$\begin{array}{l} \text{Act : } \frac{(a, s) \longrightarrow s'}{\text{true}} \quad \text{if } s \models \text{Pre}(a) \text{ and } s' = \text{Post}(a, s) \\ \text{special case: assignment } \frac{(x := v, s) \longrightarrow s'}{\text{true}} \quad \text{if } s' = s[x = v] \\ \\ \text{Skip : } \frac{(\text{skip}, s) \longrightarrow s}{\text{true}} \\ \\ \text{Seq : } \frac{(\delta_1; \delta_2, s) \longrightarrow s'}{(\delta_1, s) \longrightarrow s'' \wedge (\delta_2, s'') \longrightarrow s'} \\ \\ \text{if : } \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \longrightarrow s'}{(\delta_1, s) \longrightarrow s'} \quad \text{if } s \models \phi \quad \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \longrightarrow s'}{(\delta_2, s) \longrightarrow s'} \quad \text{if } s \models \neg \phi \\ \\ \text{while : } \frac{(\text{while } \phi \text{ do } \delta, s) \longrightarrow s}{\text{true}} \quad \text{if } s \models \neg \phi \quad \frac{(\text{while } \phi \text{ do } \delta, s) \longrightarrow s'}{(\delta, s) \longrightarrow s'' \wedge (\text{while } \phi \text{ do } \delta, s'') \longrightarrow s'} \quad \text{if } s \models \phi \end{array}$$

Structural rules

The structural rules have the following schema:

$$\frac{\text{CONSEQUENT}}{\text{ANTECEDENT}} \quad \text{if SIDE-CONDITION}$$

which is to be interpreted logically as:

$$\forall (\text{ANTECEDENT} \wedge \text{SIDE-CONDITION} \supset \text{CONSEQUENT})$$

where $\forall Q$ stands for the universal closure of all free variables occurring in Q , and, typically, ANTECEDENT, SIDE-CONDITION and CONSEQUENT share free variables.

The structural rules define inductively a relation, namely: **the smallest relation satisfying the rules.**

Examples

Example (evaluation semantics)

Compute s_f in the following cases, assuming that in the memory state S_0 we have $x = 10$ and $y = 0$:

- $(x := x + 1; x := x * 2, S_0) \longrightarrow s_f$
- $(x := x + 1;$
 if $(x < 10)$ **then** $x := 0$ **else** $x := 1;$
 $x := x + 1, S_0) \longrightarrow s_f$
- $(y := 0; \textbf{while } (y < 4) \textbf{ do } \{x := x * 2; y := y + 1\}, S_0) \longrightarrow s_f$

Transition semantics

Idea: describe the result of executing a **single step** of the program.

Transition semantics

- Given a program δ and a memory state s compute the memory state s' and the program δ' that remains to be executed obtained by executing a single step of δ in s .
- Assert when a program δ can be considered **successfully terminated** in a memory state s .

Transition semantics

More formally:

Transition semantics

- Define the **relation** “*Trans*” denoted by “ \longrightarrow ”:

$$(\delta, s) \longrightarrow (\delta', s')$$

where δ is a program, s is the memory state in which the program is executed, and s' is the memory state obtained by executing a single step of δ and δ' is what remains to be executed of δ after such a single step.

- Define a **predicate** “*Final*” and denoted by “ \checkmark ”:

$$(\delta, s)^\checkmark$$

where δ is a program that can be considered (successfully) terminated in the memory state s .

Such a relation and predicate can be defined inductively in a standard way, using the so called **transition (structural) rules**

Transition semantics: references

The general approach we follow is the *structural operational semantics* approach [Plotkin81, Nielson&Nielson99].

This single-step semantics is often called: *transition semantics* or *computation semantics*.

Transition rules for **while**-programs

Transition rules for **while**-programs

$$\begin{aligned} \text{Act} : & \frac{(a, s) \longrightarrow (\epsilon, s')}{\text{true}} \quad \text{if } s \models \text{Pre}(a) \text{ and } s' = \text{Post}(a, s) \\ \text{special case: assignment} & \frac{(x := v, s) \longrightarrow (\epsilon, s')}{\text{true}} \quad \text{if } s' = s[x = v] \\ \text{Skip} : & \frac{(\text{skip}, s) \longrightarrow (\epsilon, s)}{\text{true}} \\ \text{Seq} : & \frac{(\delta_1; \delta_2, s) \longrightarrow (\delta'_1; \delta_2, s')}{(\delta_1, s) \longrightarrow (\delta'_1, s')} \quad \frac{(\delta_1; \delta_2, s) \longrightarrow (\delta'_1; \delta'_2, s')}{(\delta_2, s) \longrightarrow (\delta'_2, s')} \quad \text{if } (\delta_1, s) \checkmark \\ \text{if} : & \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \longrightarrow (\delta'_1, s')}{(\delta_1, s) \longrightarrow (\delta'_1, s')} \quad \text{if } s \models \phi \quad \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \longrightarrow (\delta'_2, s')}{(\delta_2, s) \longrightarrow (\delta'_2, s')} \quad \text{if } s \models \neg \phi \\ \text{while} : & \frac{(\text{while } \phi \text{ do } \delta, s) \longrightarrow (\delta'; \text{while } \phi \text{ do } \delta, s')}{(\delta, s) \longrightarrow (\delta', s')} \quad \text{if } s \models \phi \end{aligned}$$

ϵ is the empty program.

Termination rules for **while**-programs

Termination rules for **while**-programs

$$\epsilon : \frac{(\epsilon, s) \checkmark}{true}$$

$$Seq : \frac{(\delta_1; \delta_2, s) \checkmark}{(\delta_1, s) \checkmark \wedge (\delta_2; s) \checkmark}$$

$$if : \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \checkmark}{(\delta_1, s) \checkmark} \text{ if } s \models \phi \quad \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \checkmark}{(\delta_2, s) \checkmark} \text{ if } s \models \neg \phi$$

$$while : \frac{(\text{while } \phi \text{ do } \delta, s) \checkmark}{true} \text{ if } s \models \neg \phi \quad \frac{(\text{while } \phi \text{ do } \delta, s) \checkmark}{(\delta, s) \checkmark} \text{ if } s \models \phi$$

Structural rules (as before)

The structural rules have the following schema:

$$\frac{\text{CONSEQUENT}}{\text{ANTECEDENT}} \text{ if SIDE-CONDITION}$$

which is to be interpreted logically as:

$$\forall (\text{ANTECEDENT} \wedge \text{SIDE-CONDITION} \supset \text{CONSEQUENT})$$

where $\forall Q$ stands for the universal closure of all free variables occurring in Q , and, typically, ANTECEDENT, SIDE-CONDITION and CONSEQUENT share free variables.

The structural rules define inductively a relation, namely: **the smallest relation satisfying the rules.**

Example

Example (transition semantics)

Compute δ', s' in the following cases, assuming that in the memory state S_0 we have $x = 10$ and $y = 0$:

- $(x := x + 1; x := x * 2, S_0) \longrightarrow (\delta', s')$
- $(x := x + 1; \text{if } (x < 10) \text{ then } x := 0 \text{ else } x := 1; x := x + 1, S_0) \longrightarrow (\delta', s')$
- $(y := 0; \text{while } (y < 4) \text{ do } \{x := x * 2; y := y + 1\}, S_0) \longrightarrow (\delta', s')$

Evaluation vs. transition semantics

How do we characterize a whole computation using single steps?

First we define the relation, named $Trans^*$, denoted by \longrightarrow^* by the following rules:

Reflexive-transitive closure of single steps: " \longrightarrow^* "

$$\begin{array}{l} 0 \text{ step : } \frac{(\delta, s) \longrightarrow^* (\delta, s)}{true} \\ \\ n \text{ step : } \frac{(\delta, s) \longrightarrow^* (\delta'', s'')}{(\delta, s) \longrightarrow (\delta', s') \wedge (\delta', s') \longrightarrow^* (\delta'', s'')} \quad (\text{for some } \delta', s') \end{array}$$

Notice that such relation is the **reflexive-transitive closure** of (single step) \longrightarrow .

Then it can be shown that:

Theorem

For every **while-program** δ and states s and s_f :

$$(\delta, s_0) \longrightarrow s_f \quad \equiv \quad (\delta, s_0) \longrightarrow^* (\delta_f, s_f) \wedge (\delta_f, s_f)^\vee \quad \text{for some } \delta_f$$

Example

Example (Computing evaluation through repeated transitions)

Compute s_f , using the definition based on \longrightarrow^* , in the following cases, assuming that in the memory state S_0 we have $x = 10$ and $y = 0$:

- $(x := x + 1; x := x * 2, S_0) \longrightarrow s_f$
- $(x := x + 1;$
 if $(x < 10)$ **then** $x := 0$ **else** $x := 1;$
 $x := x + 1, S_0) \longrightarrow s_f$
- $(y := 0; \textbf{while } (y < 4) \textbf{ do } \{x := x * 2; y := y + 1\}, S_0) \longrightarrow s_f$

Concurrency

The transition semantics extends immediately to constructs for concurrency: The evaluation semantics can still be defined but only in terms of the transition semantics (as above).

We model concurrent processes by **interleaving**: *A concurrent execution of two processes is one where the primitive actions in both processes occur, interleaved in some fashion.*

It is OK for a process to remain **blocked** for a while, the other processes will continue and eventually unblock it.

Additional constructs for concurrency

Constructs for concurrency

$(\delta_1 \parallel \delta_2)$	concurrent execution
if ϕ then δ_1 else δ_2	synchronized conditional
while ϕ do δ	synchronized loop

For the latter, we observe that our transition rules for **if** and **while** enforce already synchronization': *testing the condition ϕ does not involve a transition per se, the evaluation of the condition and the first action of the branch chosen are executed as an atomic unit.*

*Note: synchronized **if** and **while** are similar to test-and-set atomic instructions used to build semaphores in concurrent programming.*

Additional transition and termination rules for concurrency

The construct $\delta_1 \parallel \delta_2$ is genuinely new.

It represents concurrency by interleaving:

Transition and termination rules for concurrency

$$\begin{array}{l} \text{transition :} \quad \frac{(\delta_1 \parallel \delta_2, s) \longrightarrow (\delta'_1 \parallel \delta_2, s')}{(\delta_1, s) \longrightarrow (\delta'_1, s')} \quad \frac{(\delta_1 \parallel \delta_2, s) \longrightarrow (\delta_1 \parallel \delta'_2, s')}{(\delta_2, s) \longrightarrow (\delta'_2, s')} \\ \\ \text{termination :} \quad \frac{(\delta_1 \parallel \delta_2, s) \checkmark}{(\delta_1, s) \checkmark \wedge (\delta_2, s) \checkmark} \end{array}$$

The presence of $\delta_1 \parallel \delta_2$ makes the transition relation **nondeterministic** (NB: "devilish nondeterminism").