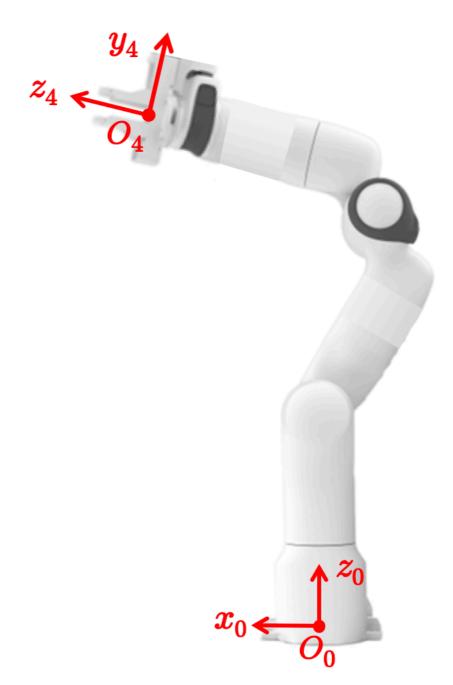
4R robot – DH frames assignment and table

Name:					

i	$lpha_i$	a_i	d_i	$\underline{\theta_i}$
1				·
2				
3				
4				



Robotics I – Sheet for Exercise 1, February 5, 2019